

STANLEY[®]

Security Solutions

DG SERIES SLIDE DOORS WITH MC 521 PRO CONTROL

STANLEY[®]

ACCESS TECHNOLOGIES

TECHNICAL SUPPORT : 800-422-6489

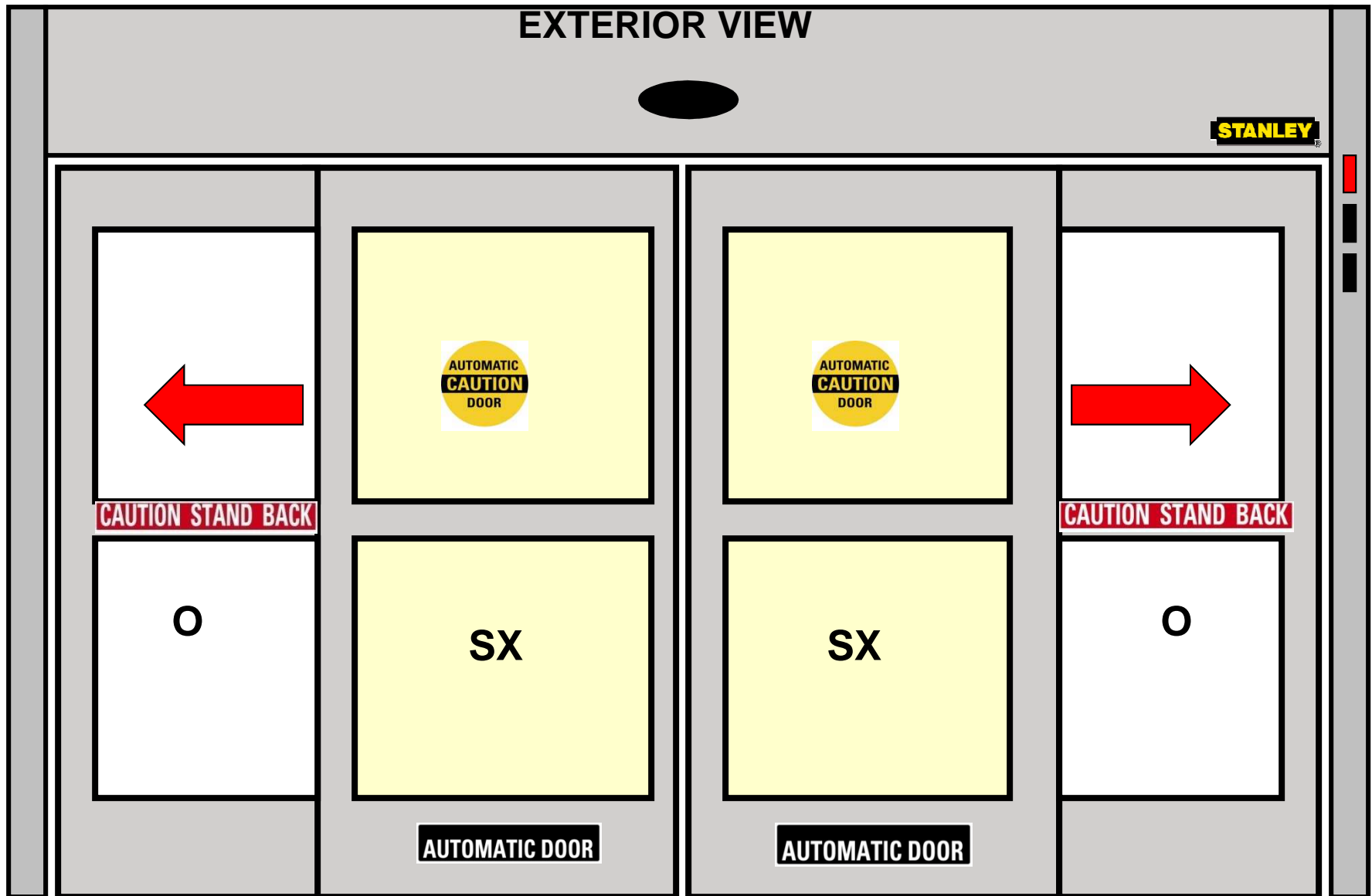
Option 3 = Jeff Bonus

Option 4 = Jim Sargent

Option 5 = Jack Karrick

2000 Package - Only SX Panels Breakout – exterior cover. **STANLEY**

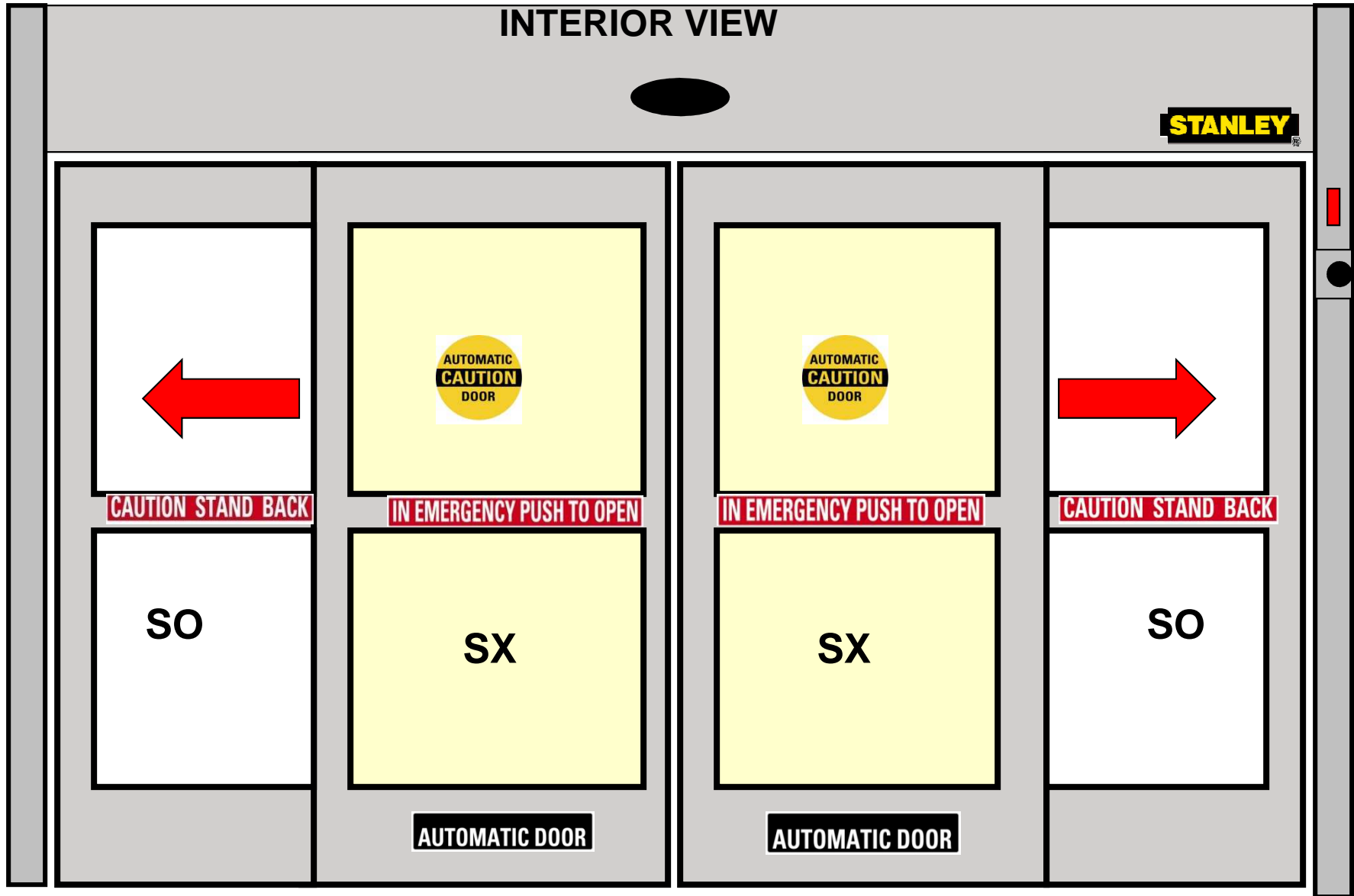
- Doors slide on exterior of building
- Only SX panels break out for emergency egress.

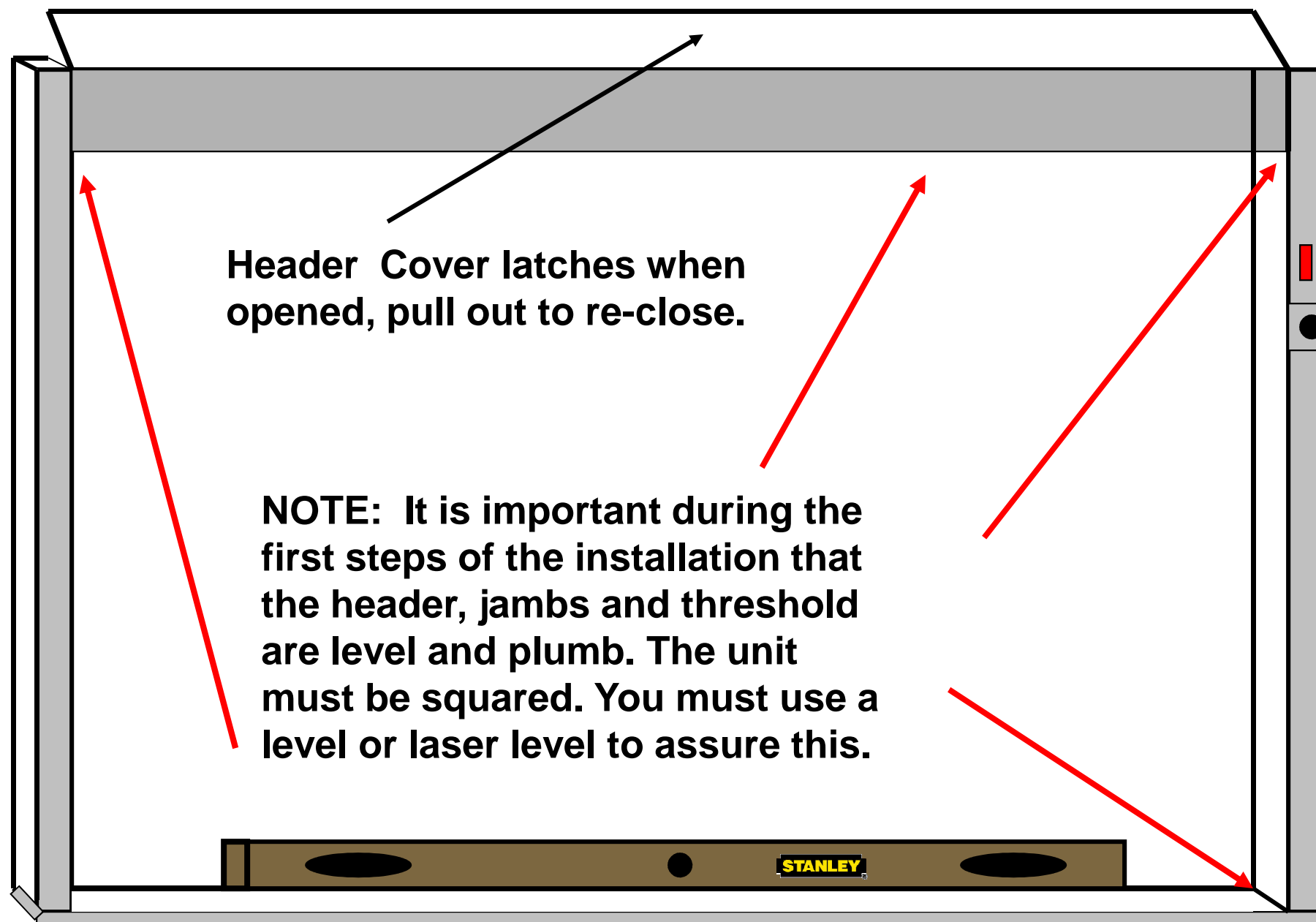


3000 Package Full Breakout – interior cover.



- All 4 panels break out for emergency egress.
- SX panels slide on interior of building.

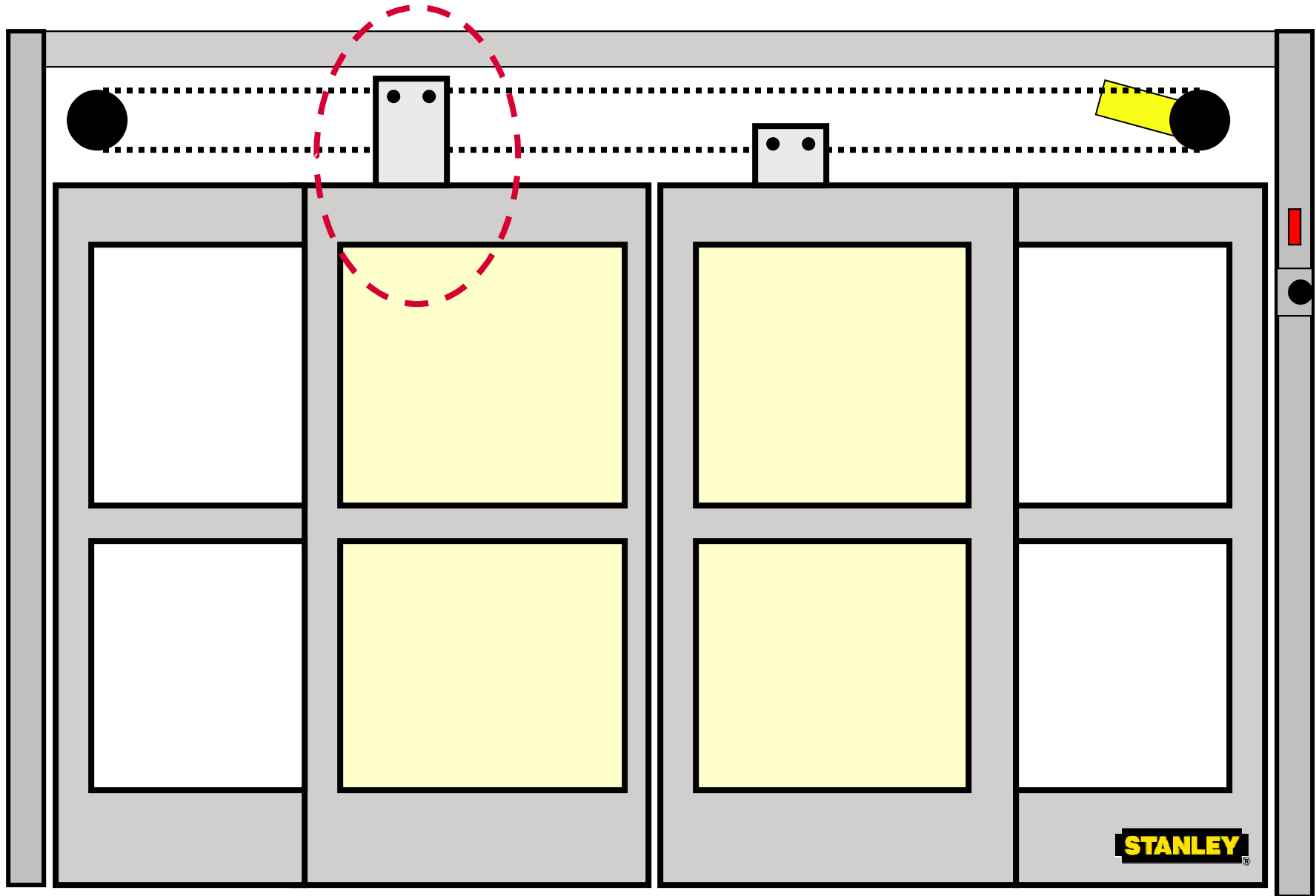


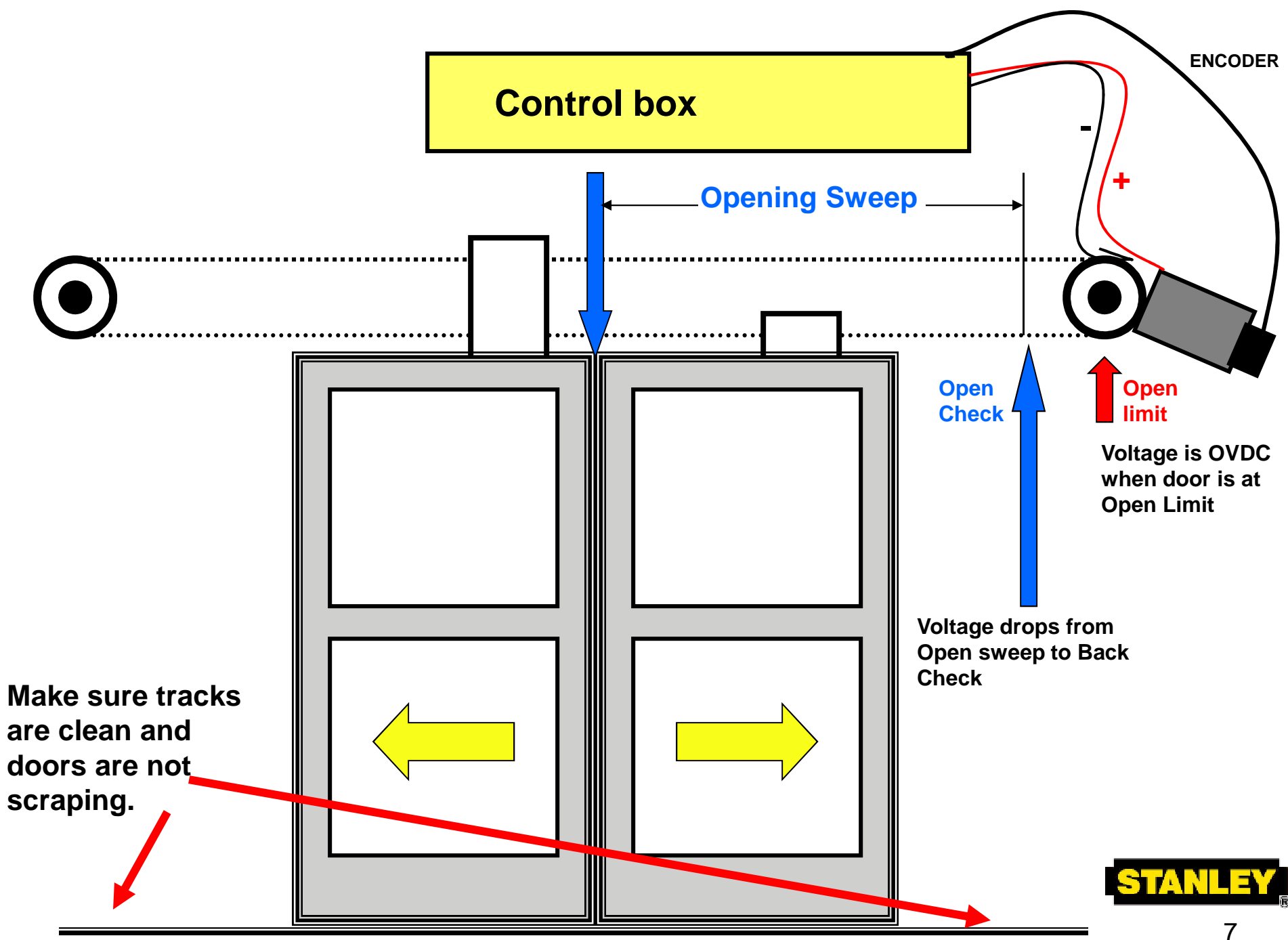


Header Cover latches when opened, pull out to re-close.

NOTE: It is important during the first steps of the installation that the header, jambs and threshold are level and plumb. The unit must be squared. You must use a level or laser level to assure this.

When hanging Bi-part sliding panels make sure the tall carrier belt bracket is on the left hand panel (*LH Panel when viewed from opened header cover*)



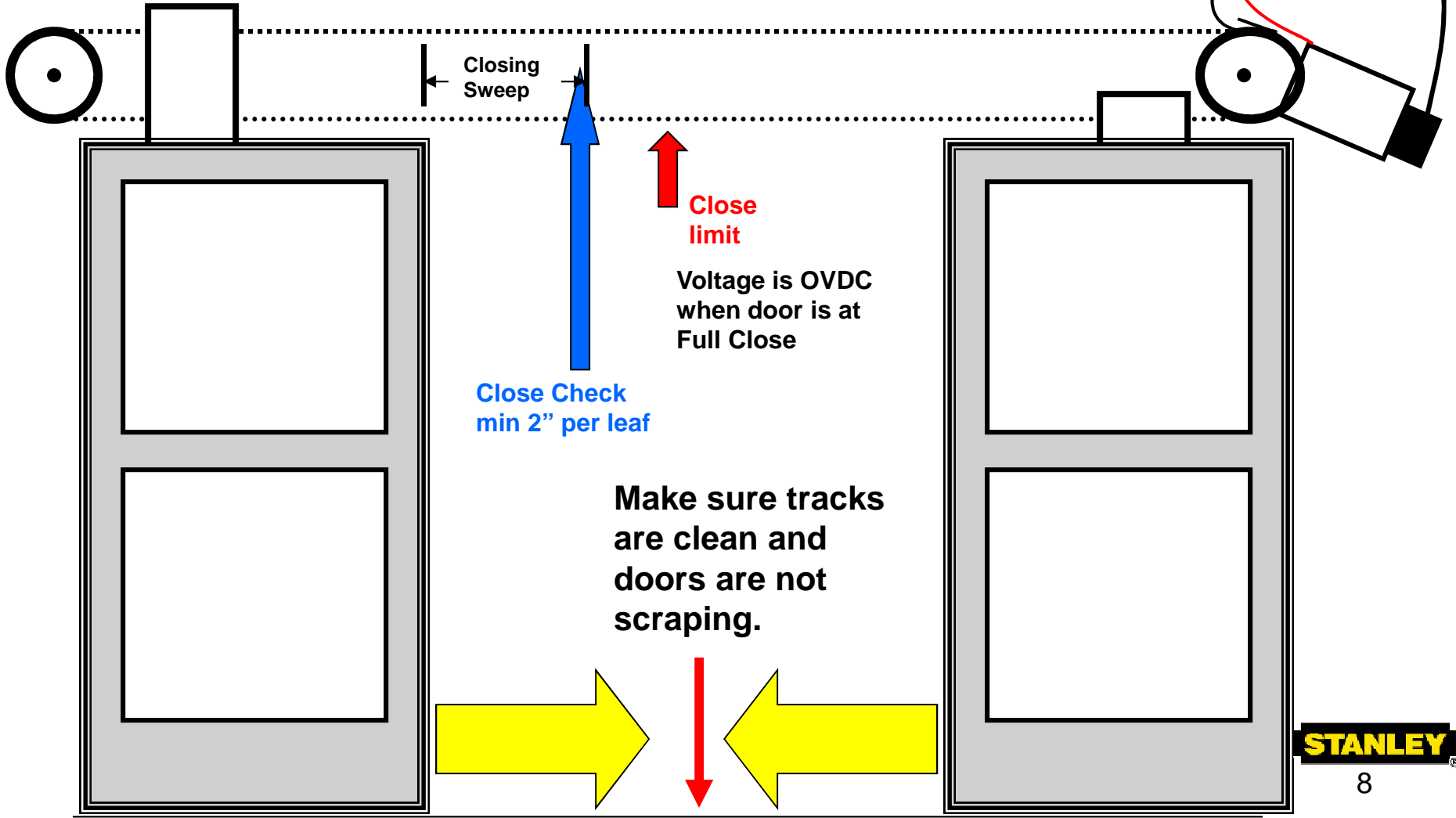


Tall carrier bracket must be on LH panel in Bi-part applications

Control box

ENCODER

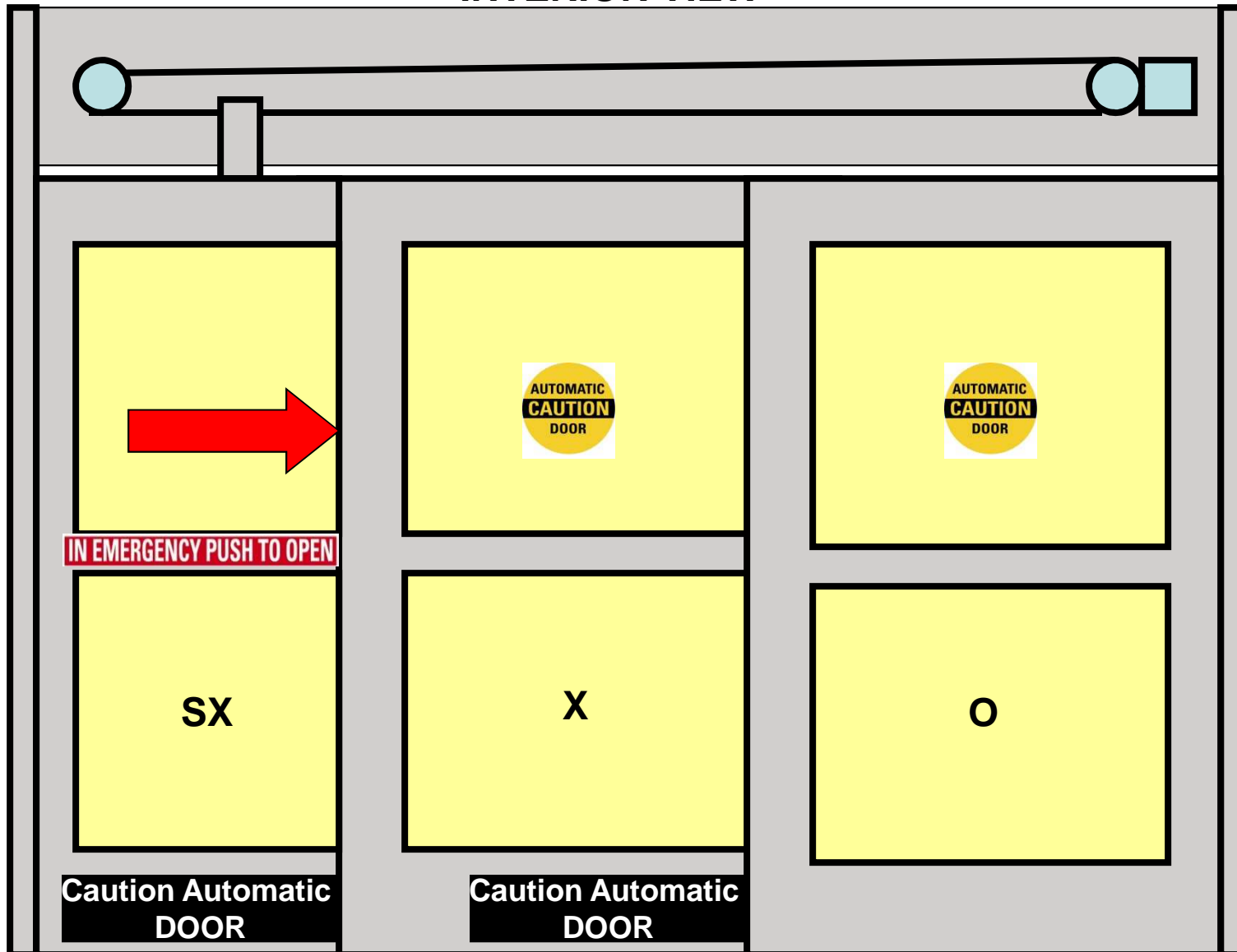
Polarity reverses on motor voltage from closing to opening sweeps.



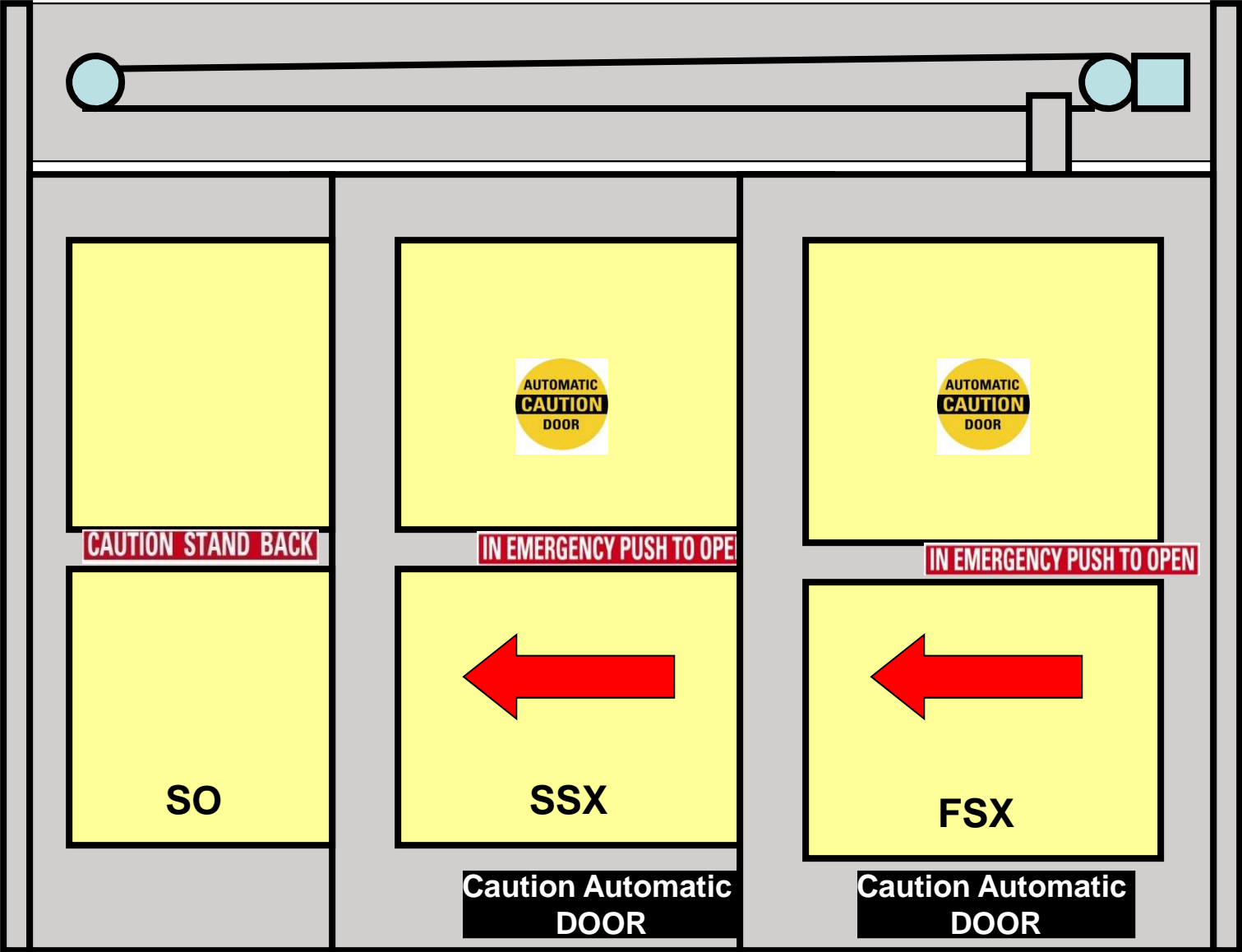
STANLEY

Stanley 5200 Telescopic Single Slide Door (Only SX panels breakout).

INTERIOR VIEW

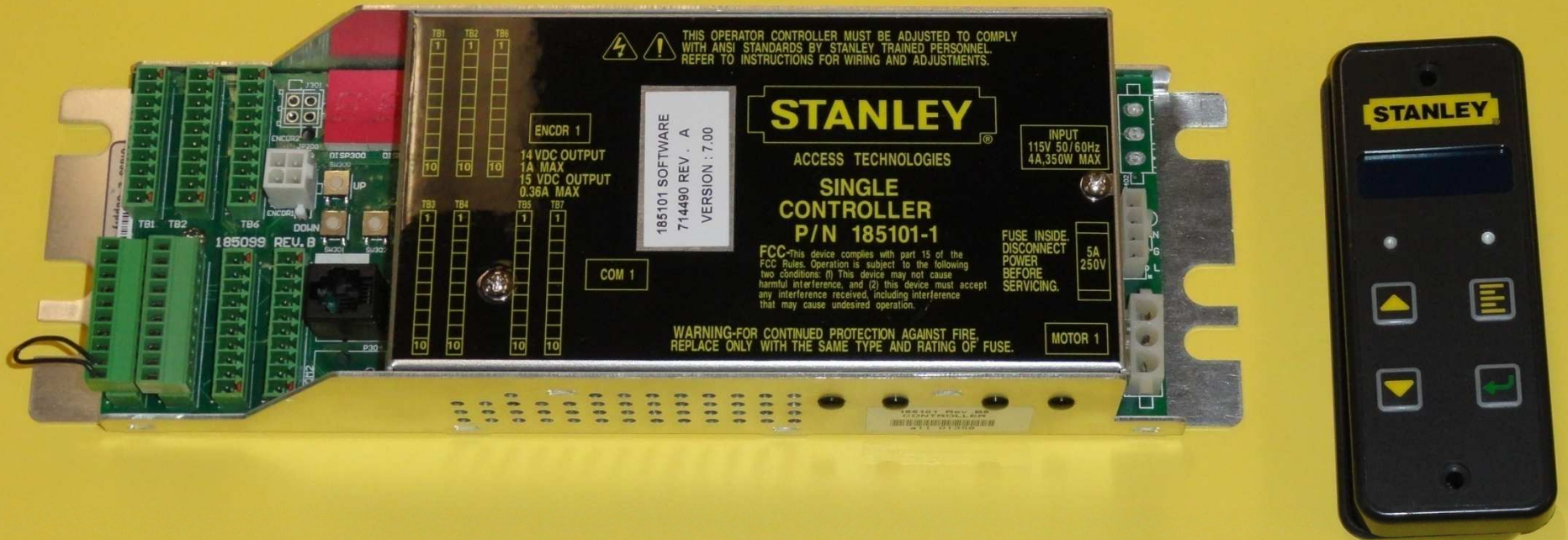


Stanley 5300 Telescopic Single Slide Door, Full Break out.



MC521PRO Control box for Sliding automatic doors

With optional ECO Switch.



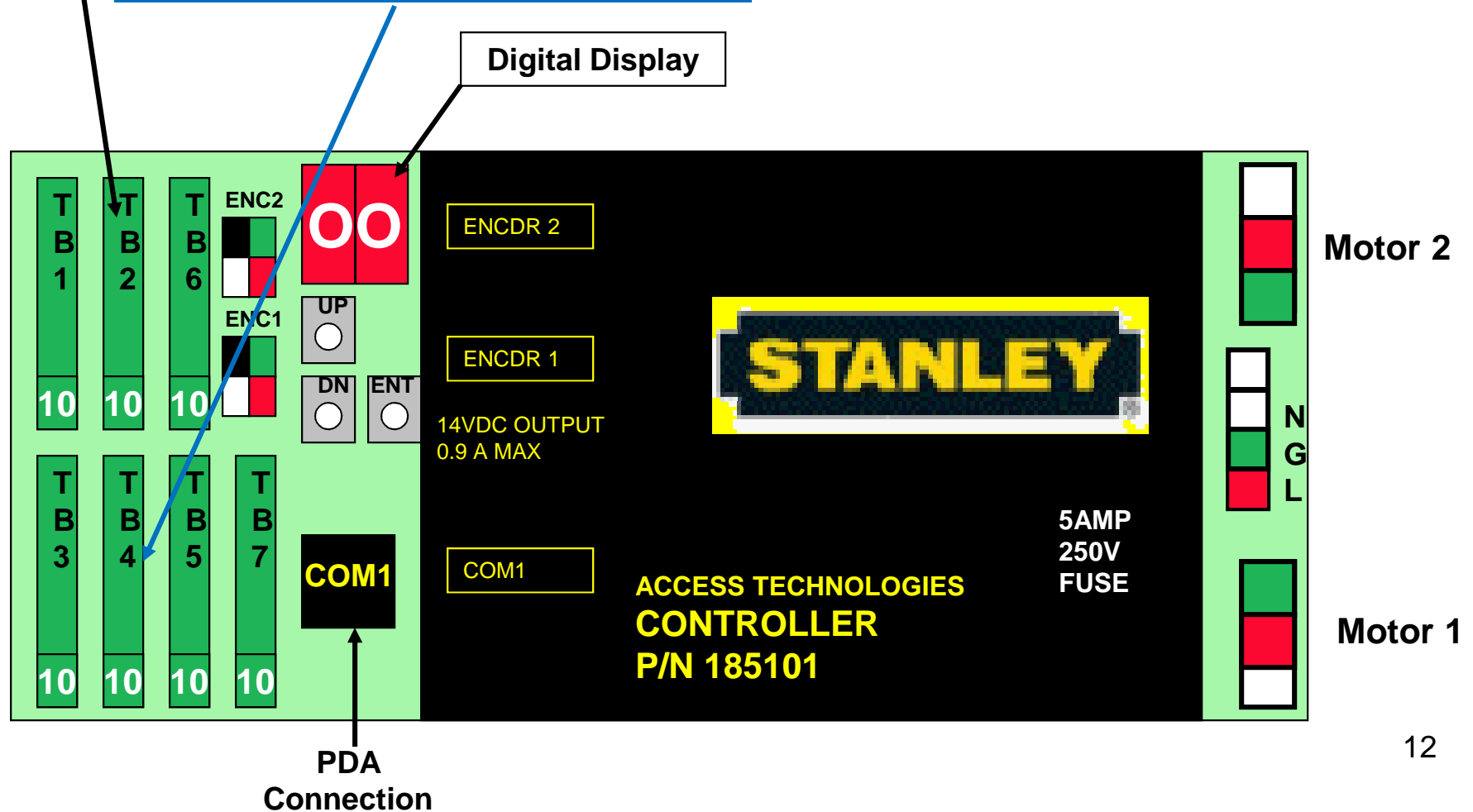
MC-521 PRO P/N 185101

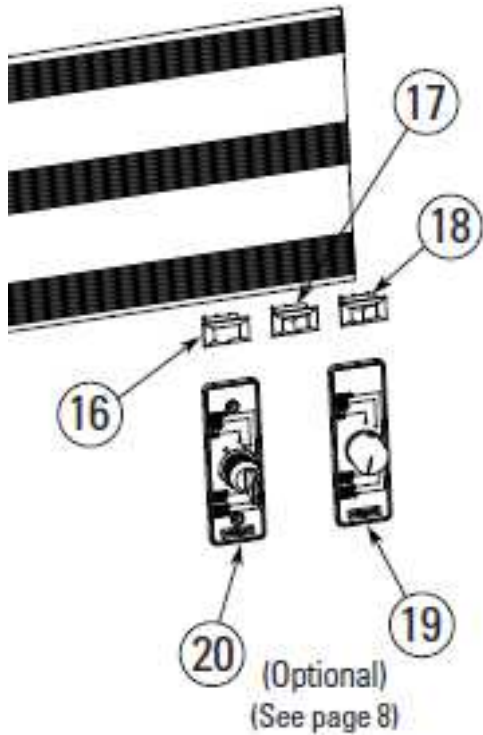
TERMINAL BLOCKS 1 THRU 7

Note: Terminals are not in sequence

One – Two – Six on top row,

Three – Four – Five – Seven on bottom row.

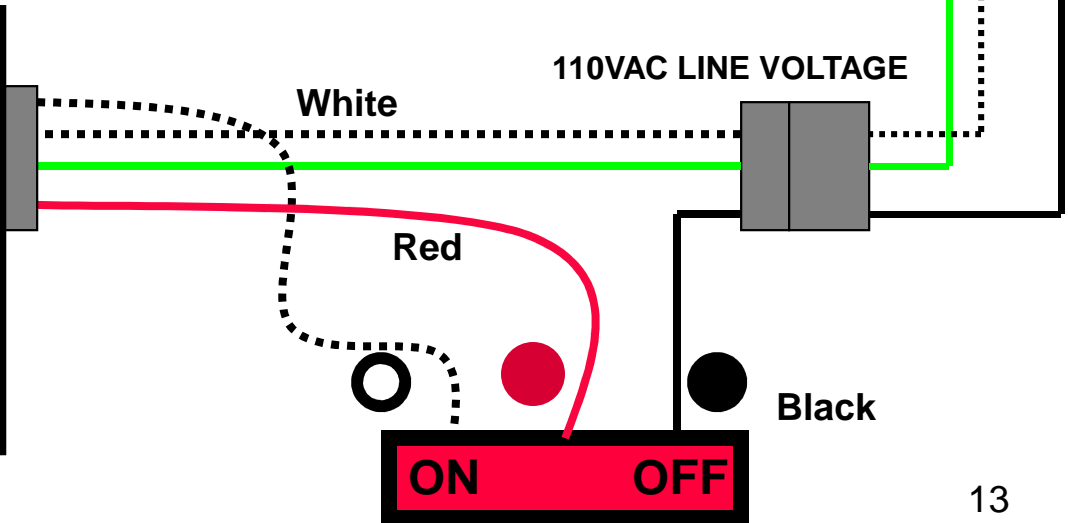
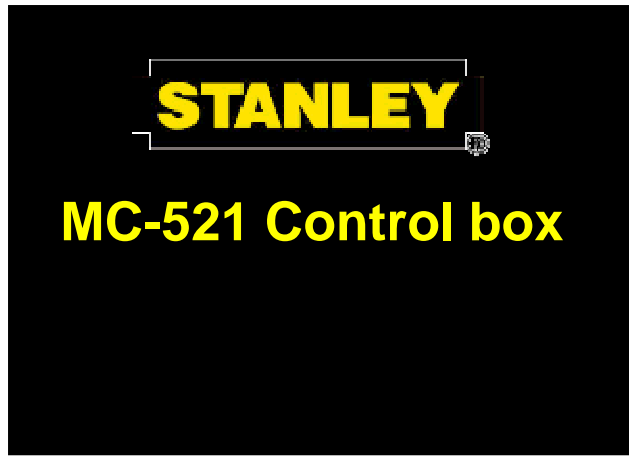
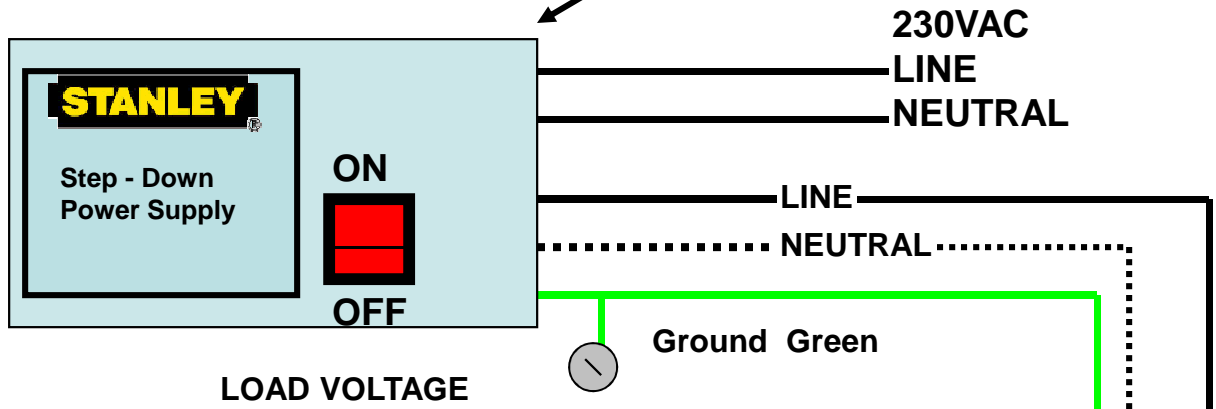




- 16713080
- 17713081
- 18713082
- 19a313719
- 413550
- 19b413960
- 20a313720
- 413584
- 714119
- 20b313720

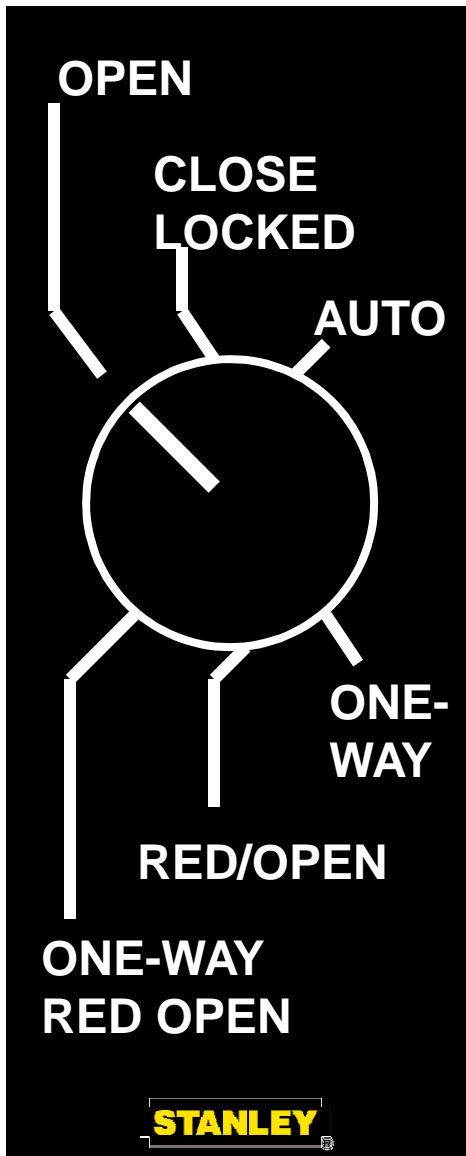
- SWITCH - ROCKER ONEWAY/RED OPEN
- SWITCH - ROCKER POWER W/LIGHT
- SWITCH - ROCKER AUTO/CLS/OPEN
- 6 POSITION KNOB SWITCH ASSY W/ HARNESS
- 6 POSITION KNOB SWITCH (Only)
- 4 POSITION KNOB SWITCH W/ HARNESS
- 6 POSITION KEY SWITCH ASSY W/ HARNESS
- 6 POSITION KEY SWITCH (Only)
- KEYS (ONLY) FOR 6 POSITION SWITCH
- 4 POSITION KEY SWITCH W/ HARNESS

Step down transformer
only needed when
incoming power exceeds
normal 110vac



Rotary switch / Key switch

NOTE: When performing FIS select Old Rotary for switch type.



OPEN, the door will open or if open will remain open until the switch function is changed. The troubleshoot screen will show TB-2 #1 BLACK

CLOSE/LOCKED, the door will close and remain closed. If a solenoid lock is installed it will latch the door. The door must be in this position to complete an FIS. The troubleshoot screen will have TB-2 terminals #1, #3, #5 & #7 WHITE.

AUTOMATIC, the door will run normally with sensors or activation/safety devices working. The troubleshoot screen will have TB-2 #3 and #5 BLACK

ONE-WAY, the sensors using TB-4 terminals #7- #8 will be inhibited when the doors are closed. When no lock is installed you must has a DPS installed and the contacts of TB-5 #7 and #8 must be shorted contact when the doors are closed and open contact all other times.

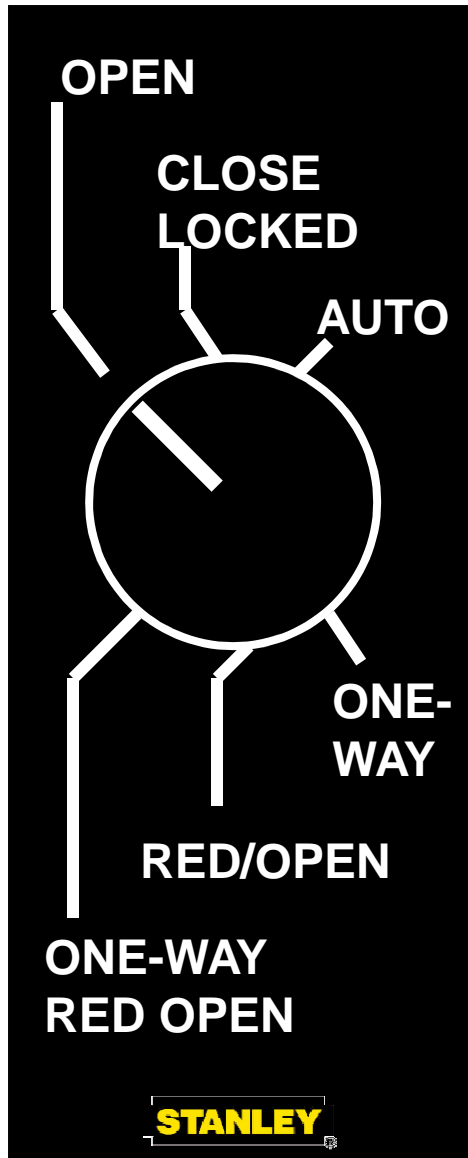
RED/OPEN, the door will only open partially. This is set on your palm or with the Index-Value buttons.

ONE-WAY/RED OPEN, the door will only open partially and will only accept one way traffic.

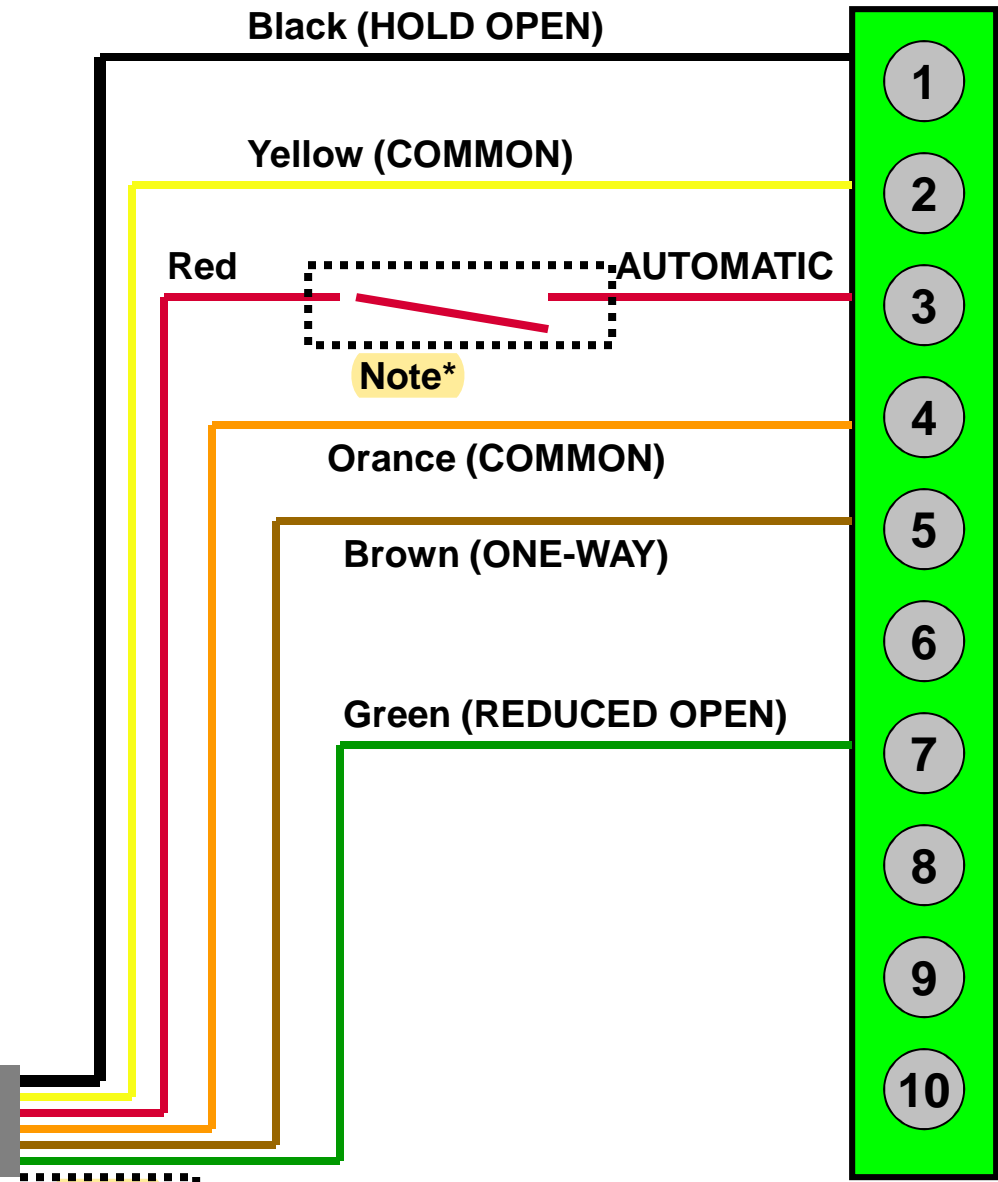
Rotary Function Switch States for TB2

	Hold Open	Closed/ Locked	Automatic	Oneway	Reduced	Reduced/ Oneway
TB2-1						
TB2-3						
TB2-5					Don't care	Don't care
TB2-7						

Rotary switch / Key switch



TB-2

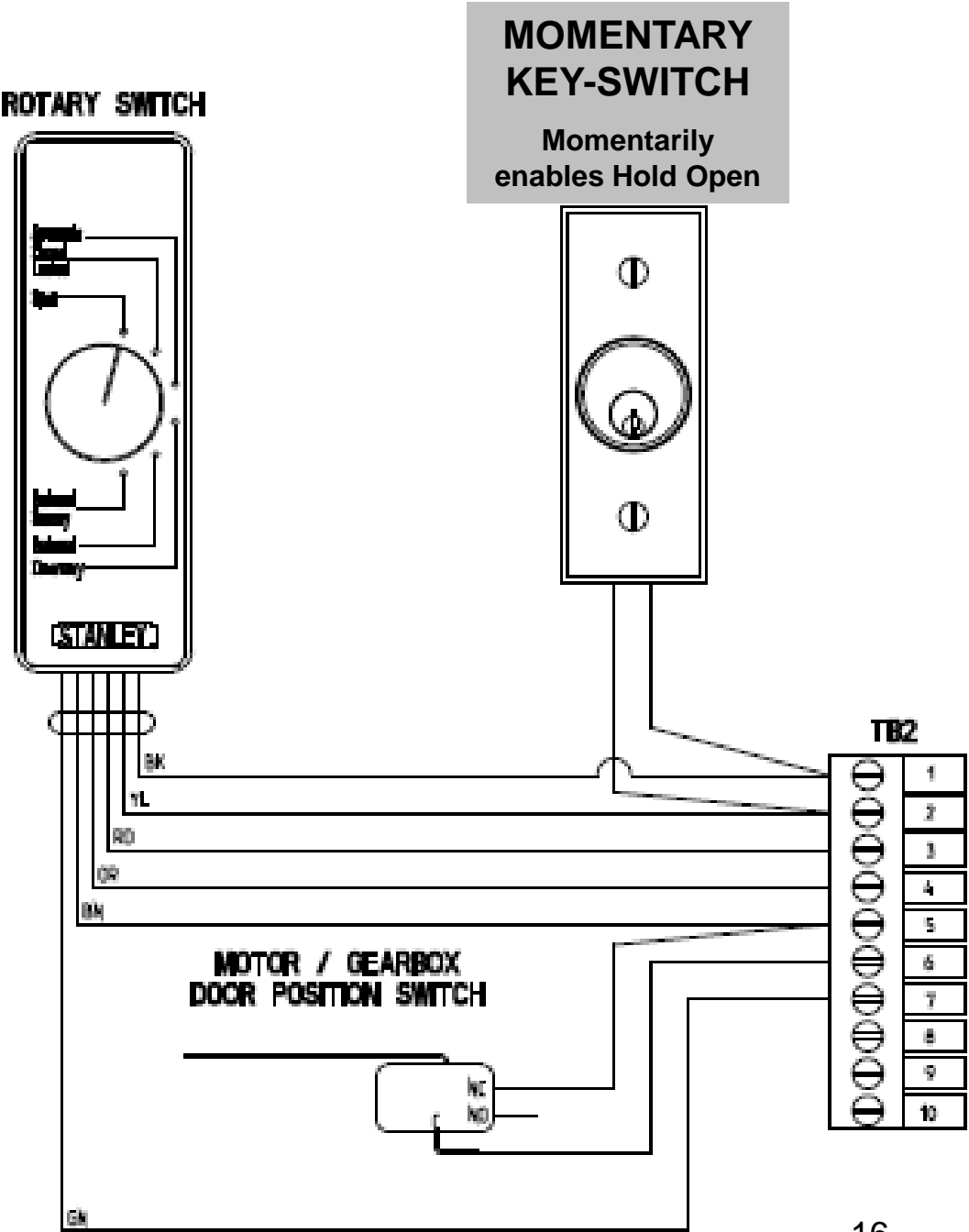


Note* To remotely put door into one way, break red wire leave function switch in automatic.

**Remote Activation
in Closed Lock
*With Rotary Switch***

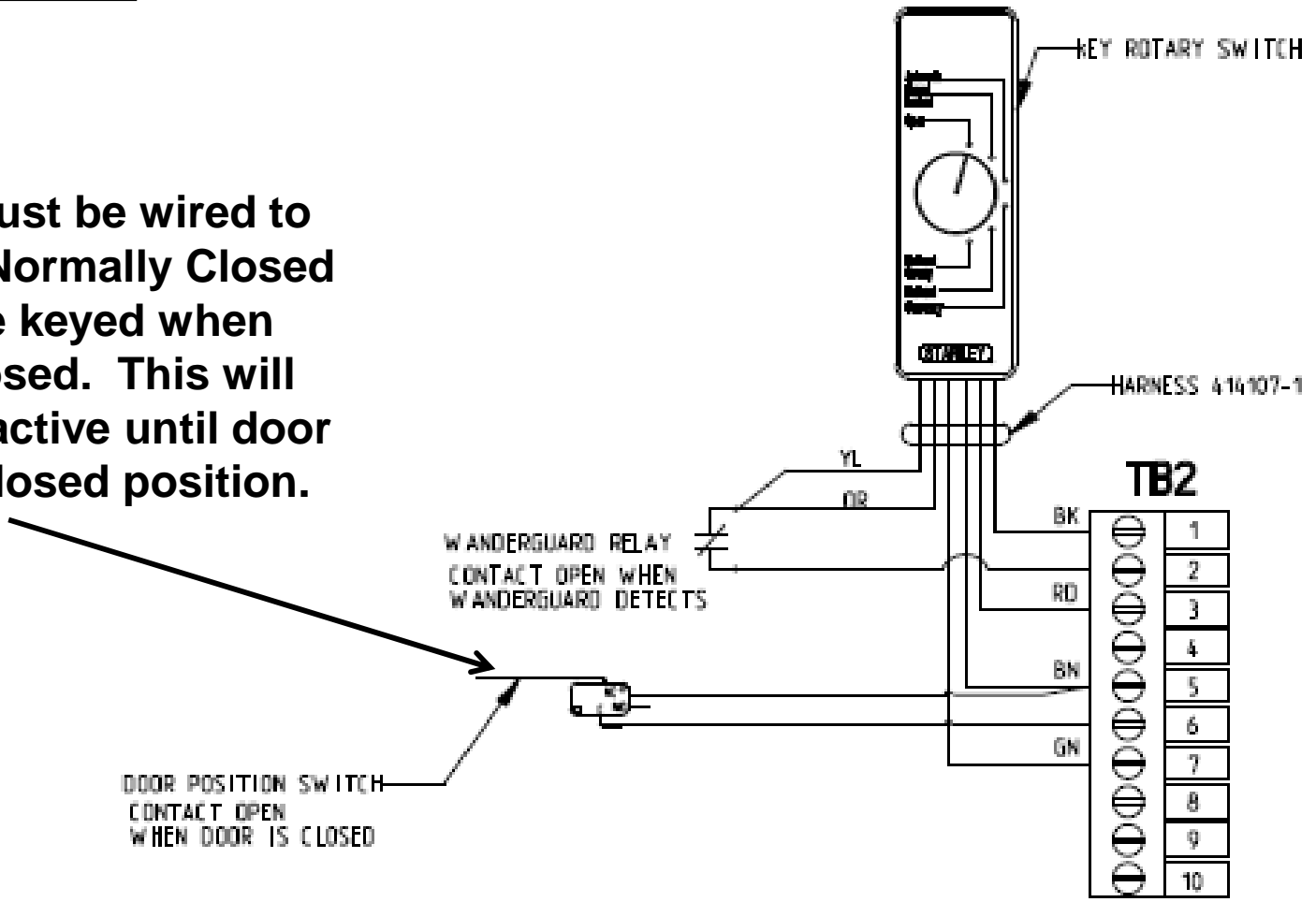
To remotely activate the slide door when in close and lock:

Belt switch must be wired to Common and Normally Closed and must be keyed when doors are closed. This will keep sensors active until door reaches full closed position.



WANDERGUARD
With Rotary Switch

Belt switch must be wired to Common and Normally Closed and must be keyed when doors are closed. This will keep sensors active until door reaches full closed position.



ROCKER SWITCHES

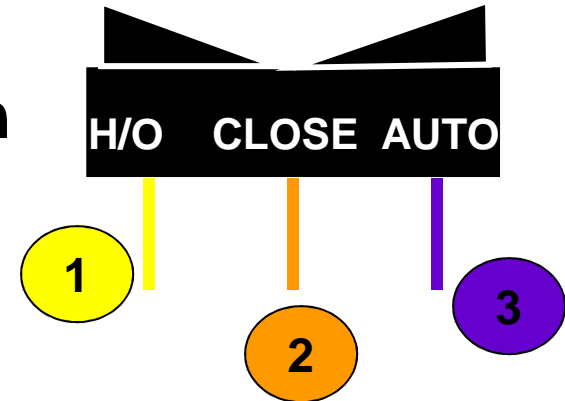
NOTE: During FIS set Function Switch Type to “Switches”

3 Pos. Rocker switch in CLOSE position

In this position the door will close if open and remain closed, if equipped with a solenoid lock it will engage.

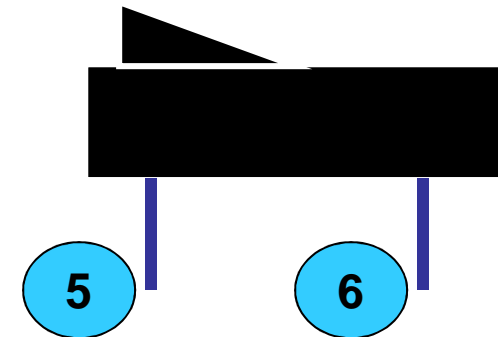
The switch must be in this position to begin an FIS.

Tb-2 term#1 yellow term#2 Orange term#3 Violet



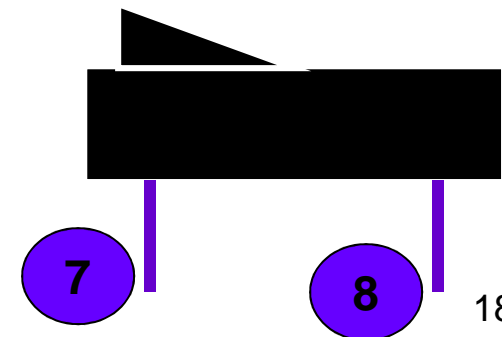
ONE WAY TRAFFIC ON//OFF switch used for door activation from one side only. Sensors will remain active on side not intended for use only when door is opened from the direction intended for use.

TB-2 terminals 5 and 6



Red ON//OFF rocker switch used for reduced open. Door will open to preset width. This switch is used to keep inclement weather out heat or air in.

TB-2 terminals 7 and 8



ROCKER SWITCHES

TB-2

ON / off /HO

Yellow (HOLD OPEN)

Orange (COMMON)

Brown (AUTOMATIC)

ENTER yes / no

Blue ENTER ONE WAY

Blue ONE WAY COMMON

RED yes / no

Violet (REDUCED OPENING)

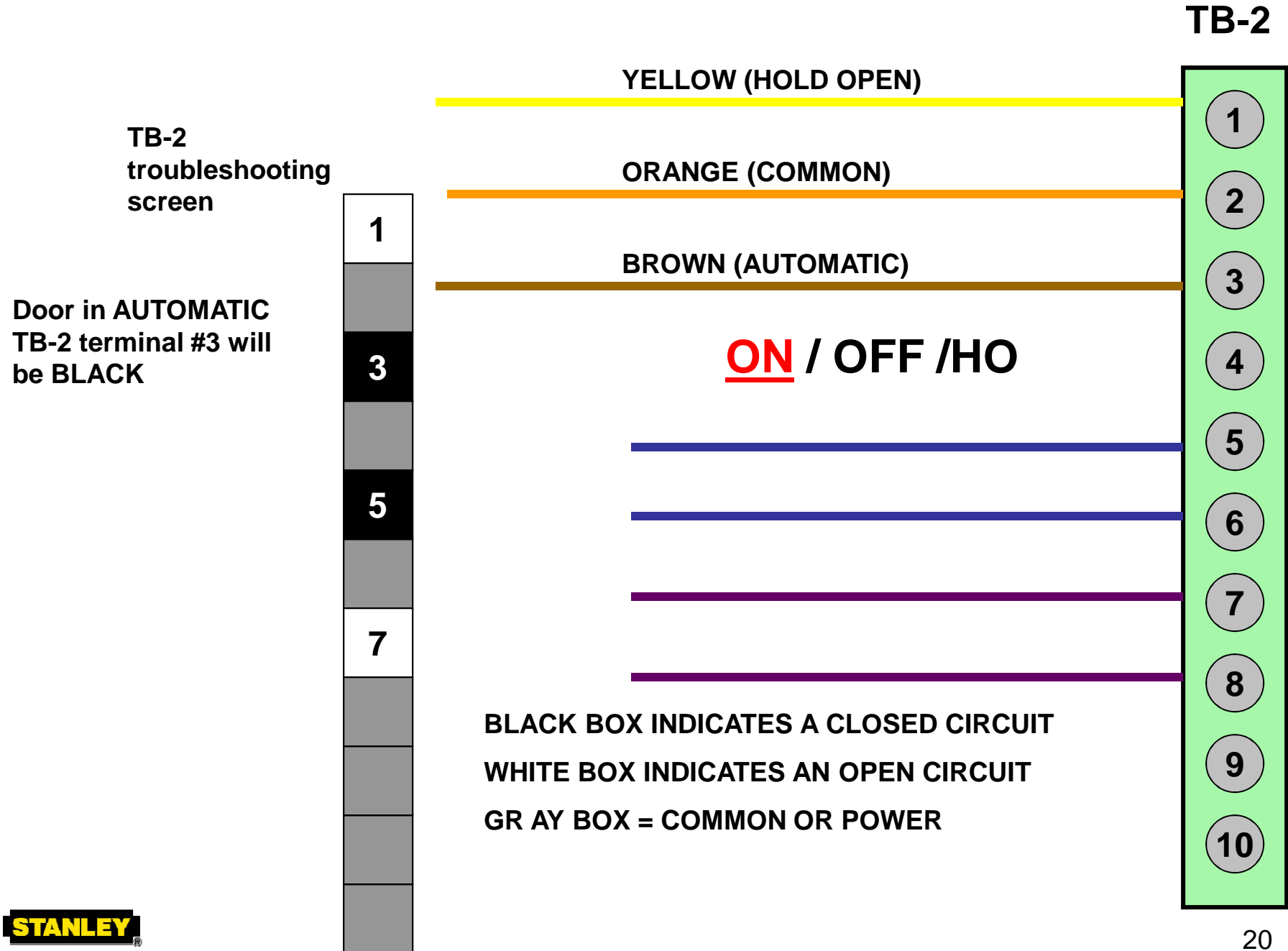
Violet (COMMON)

Rocker Function Switch States for TB2

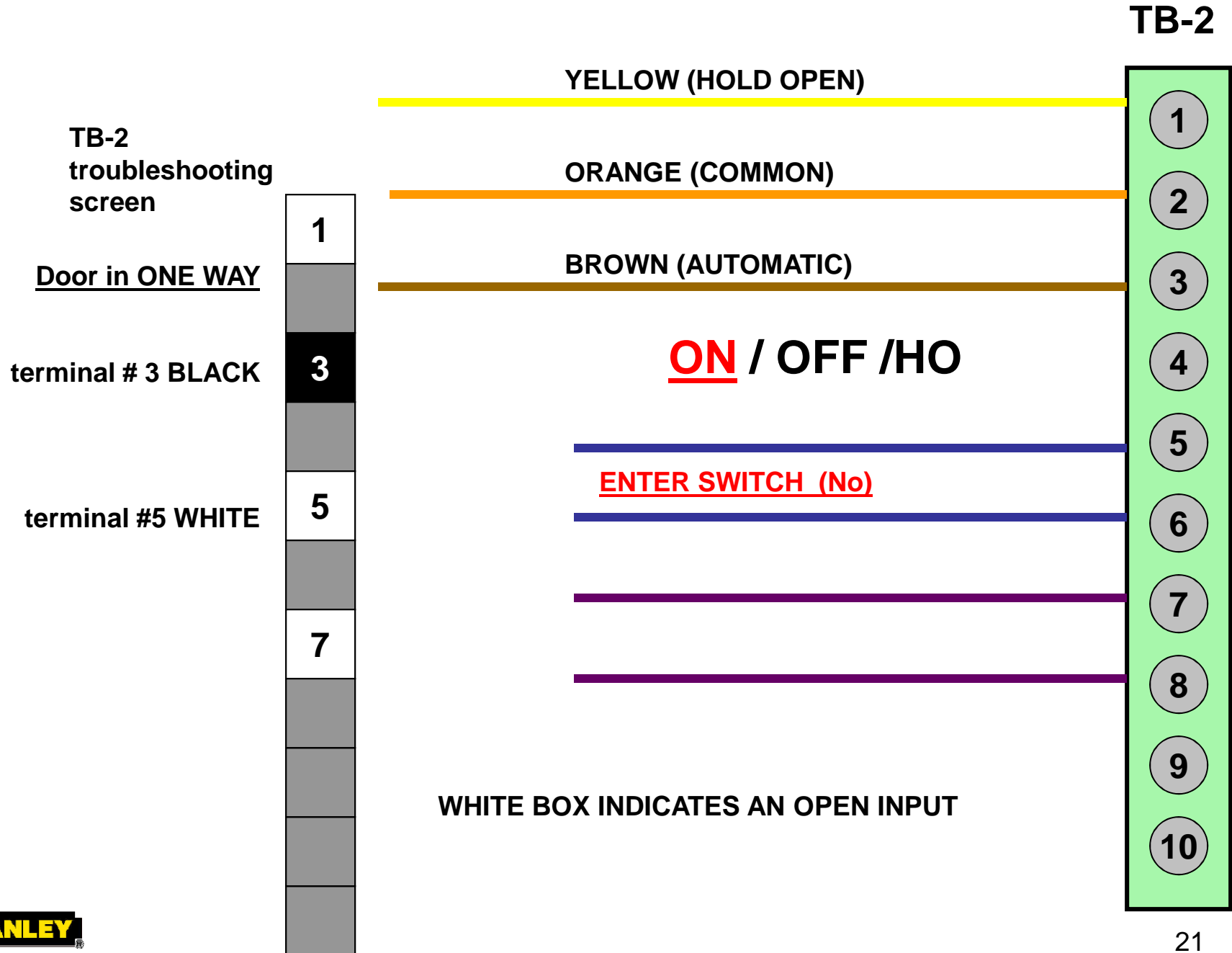
	Hold Open	Closed/ Locked	Automatic	Oneway	Reduced	Reduced/ Oneway
TB2-1						
TB2-3						
TB2-5	Don't care	Don't care				
TB2-7	Don't care	Don't care				



Rocker Switches MC521 – Slide Door

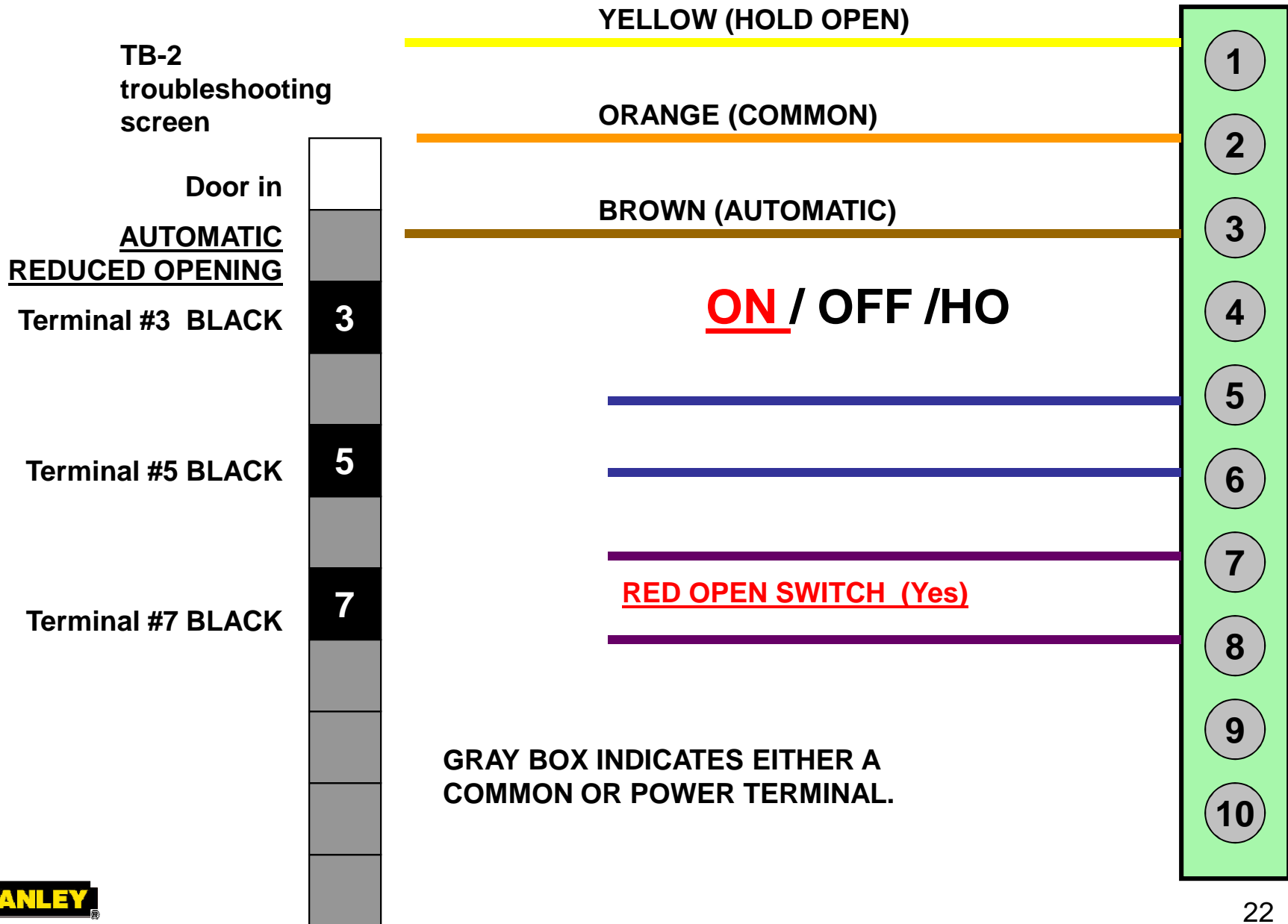


Rocker Switches MC521 – Slide Door



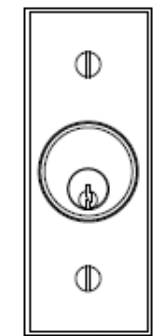
Rocker Switches MC521 – Slide Door

TB-2



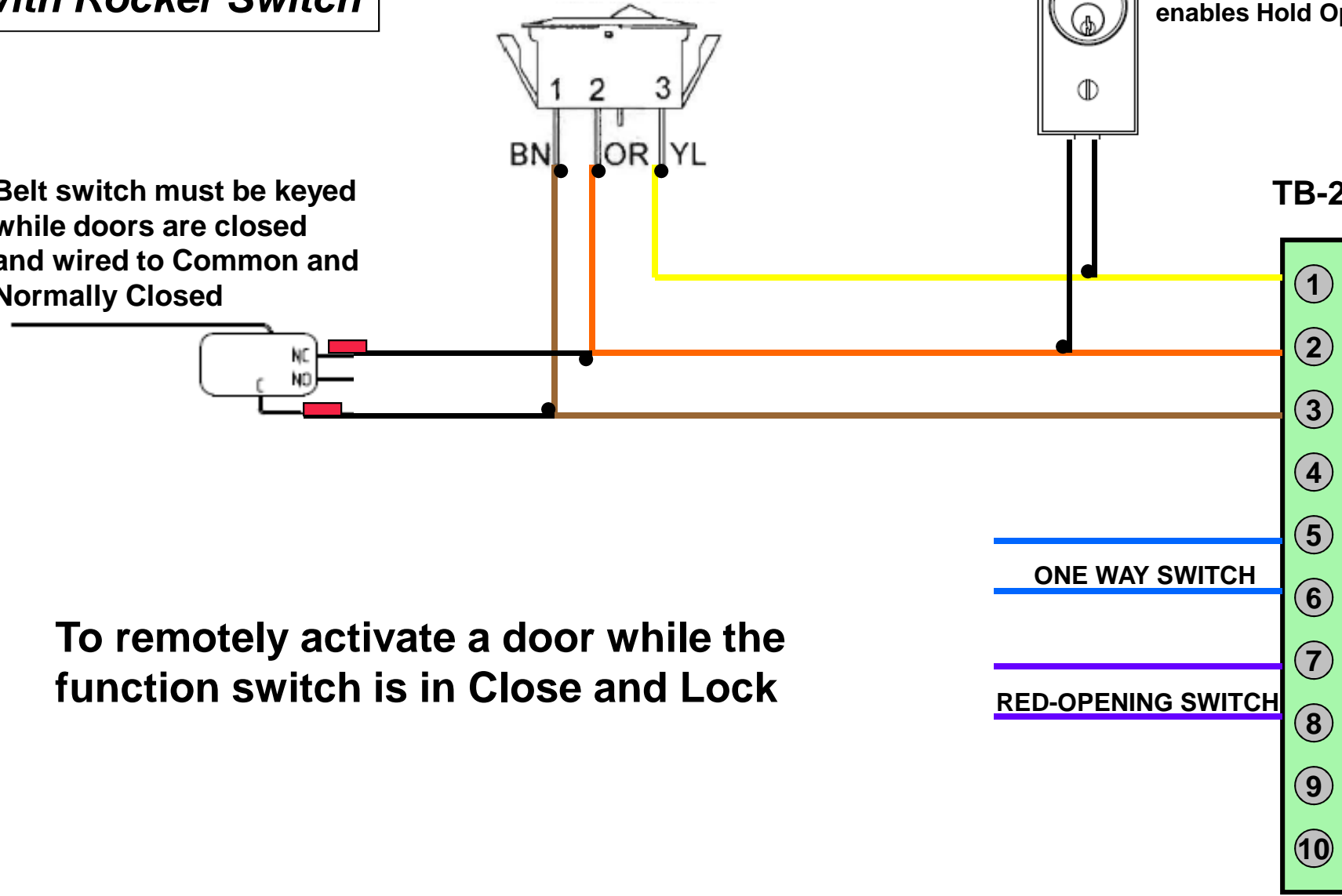
**Remote Activation
in Closed Lock
With Rocker Switch**

ON-OFF-HO SWITCH



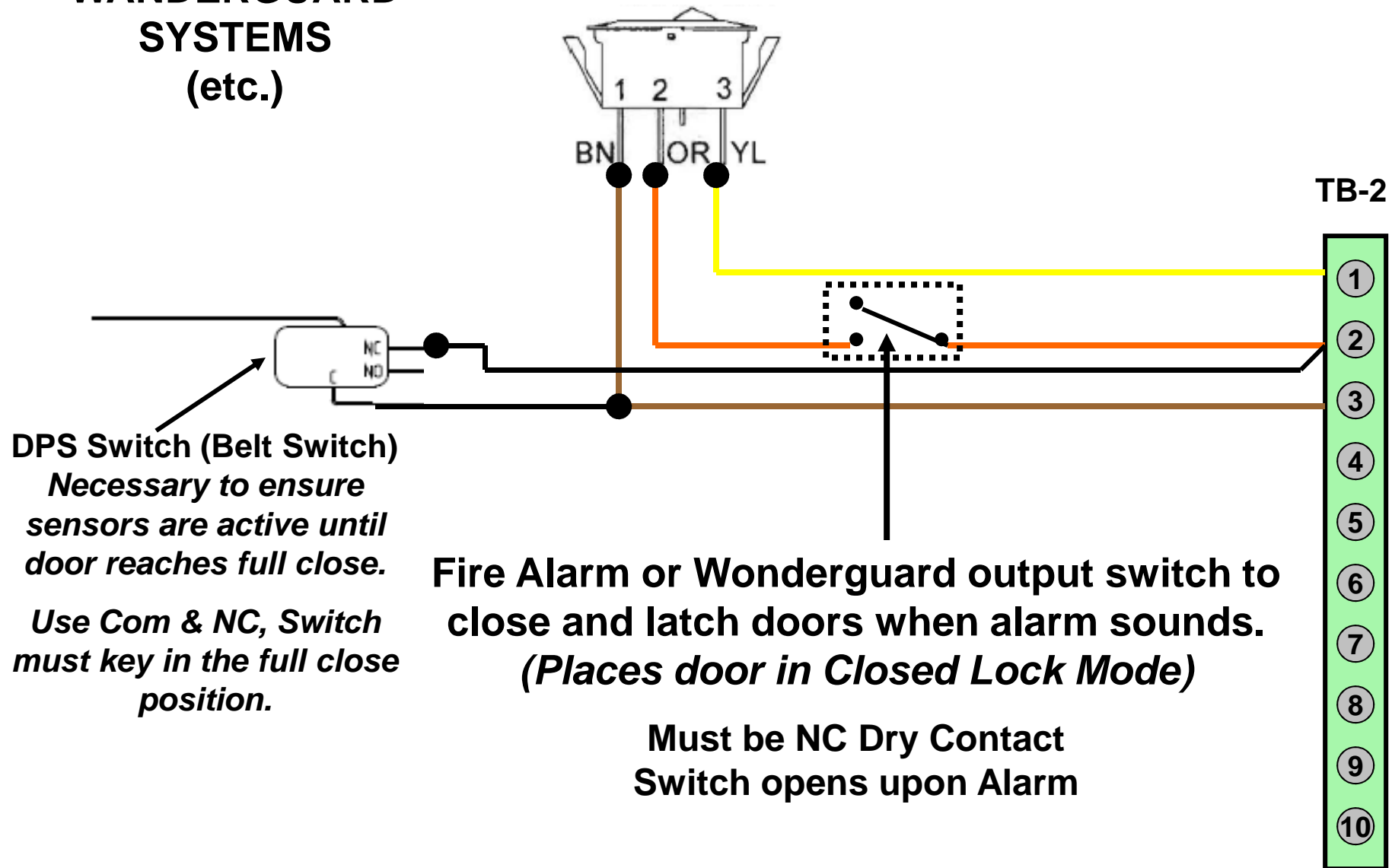
MOMENTARY KEY-SWITCH
Momentarily enables Hold Open

Belt switch must be keyed while doors are closed and wired to Common and Normally Closed



To remotely activate a door while the function switch is in Close and Lock

**OPTIONAL
FIRE ALARM SYSTEMS
OR
WANDERGUARD
SYSTEMS
(etc.)**



DPS Switch (Belt Switch)
Necessary to ensure sensors are active until door reaches full close.
Use Com & NC, Switch must key in the full close position.

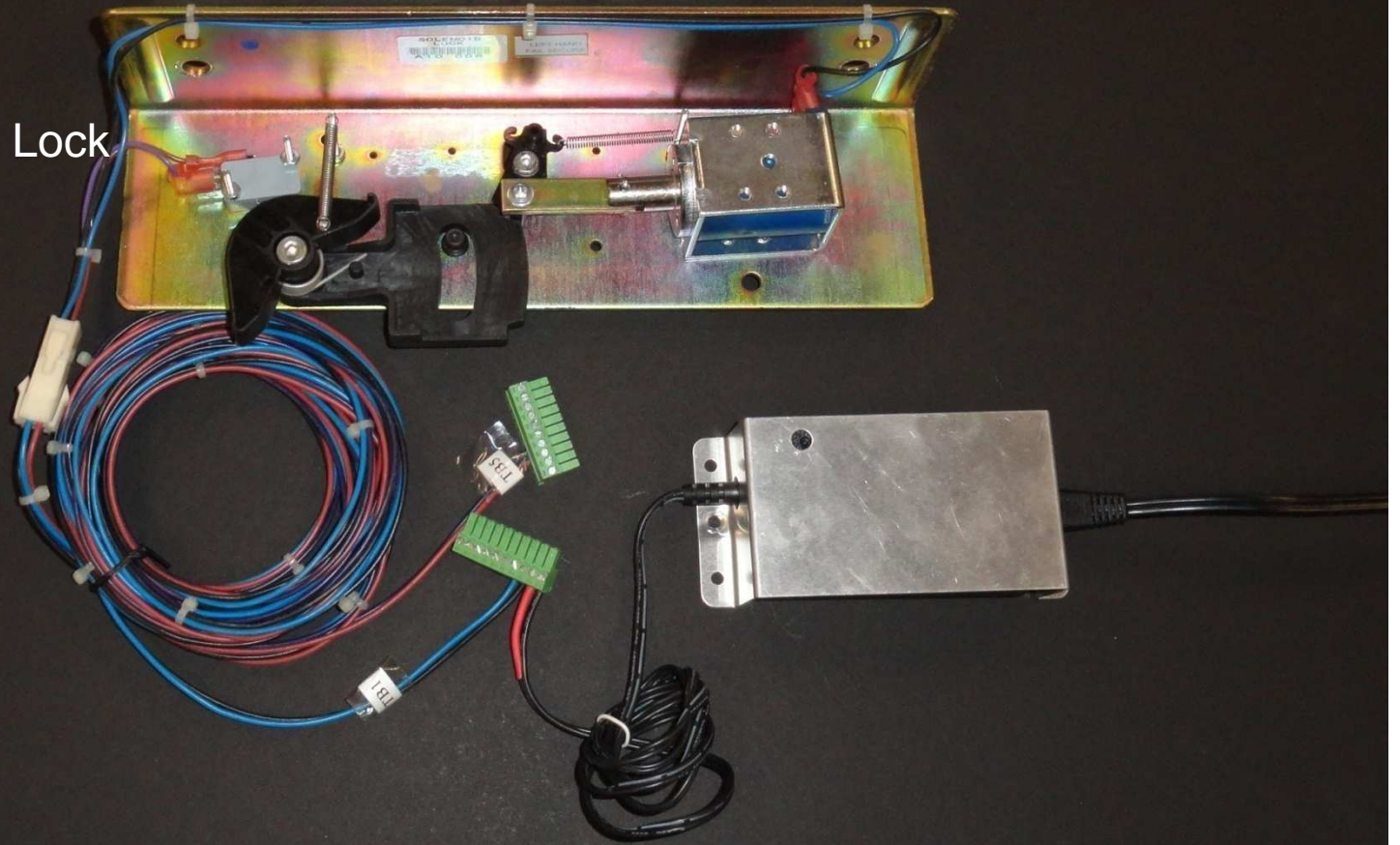
Fire Alarm or Wanderguard output switch to close and latch doors when alarm sounds.
(Places door in Closed Lock Mode)

Must be NC Dry Contact Switch opens upon Alarm

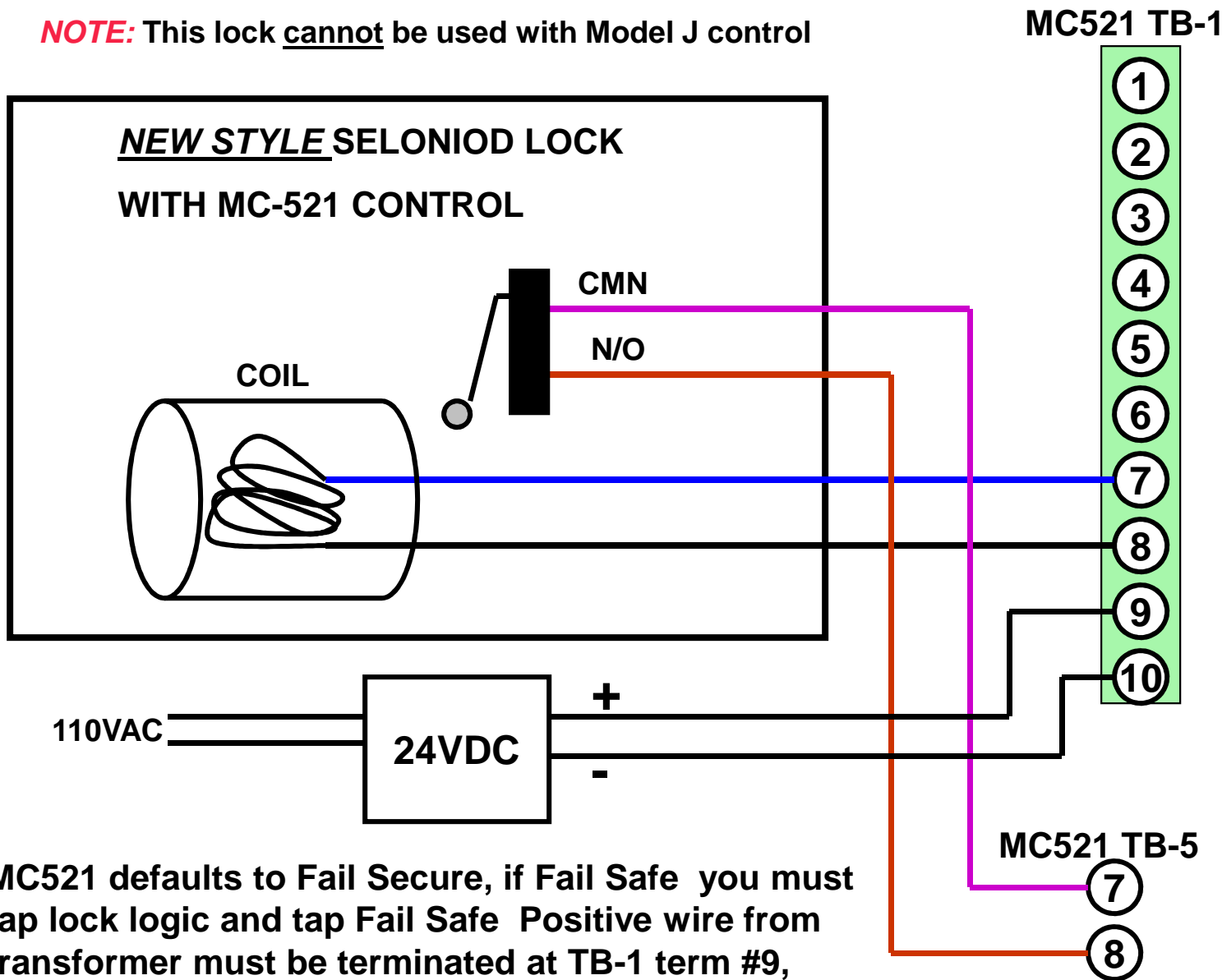
Old Style Solenoid Lock



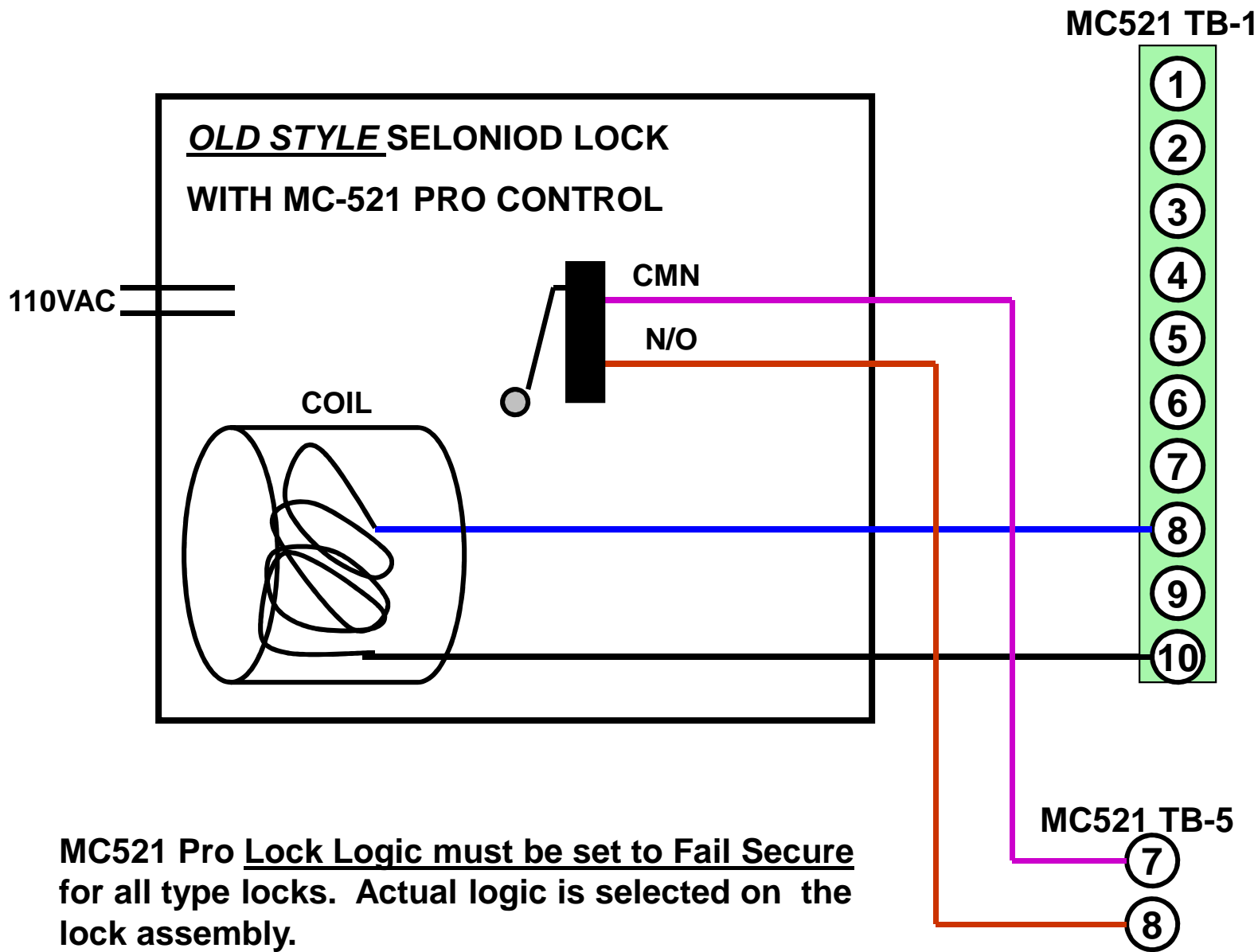
New Style Solenoid Lock



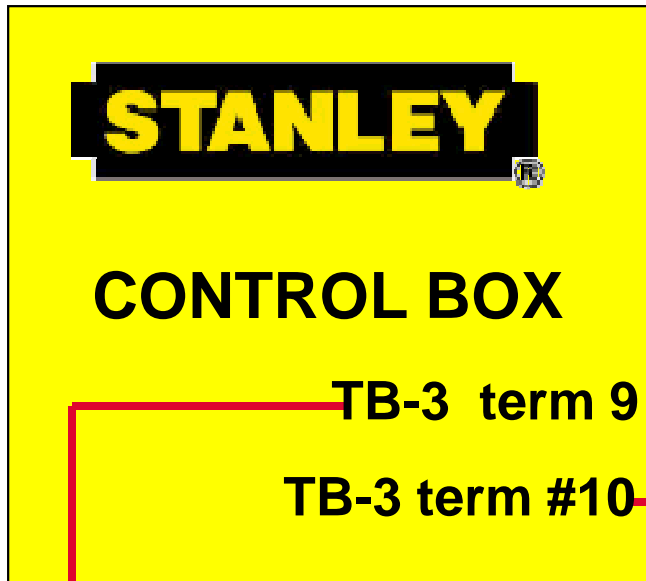
NOTE: This lock cannot be used with Model J control



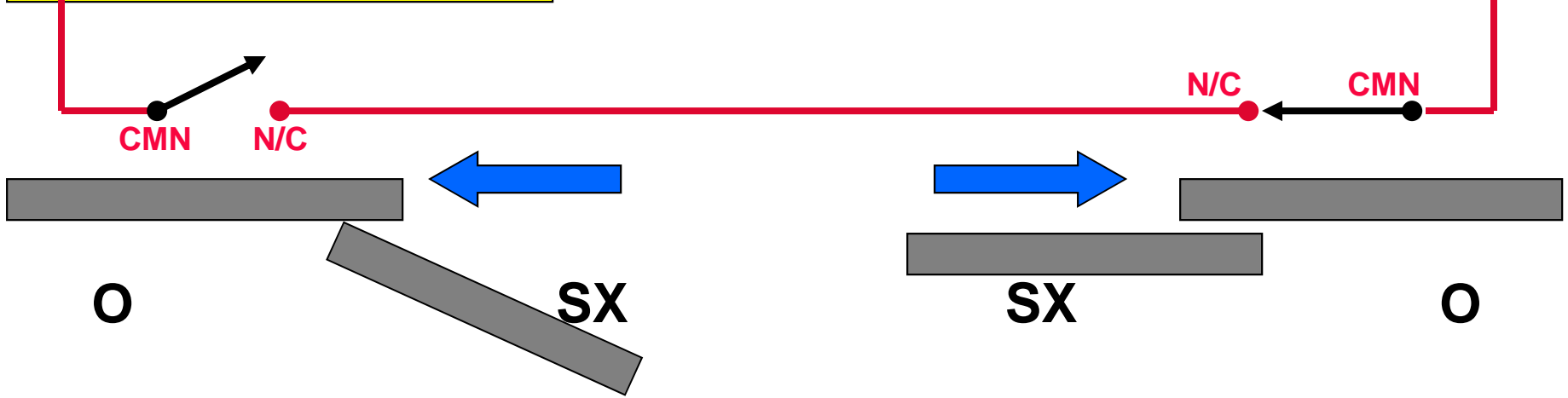
MC521 defaults to Fail Secure, if Fail Safe you must tap lock logic and tap Fail Safe Positive wire from transformer must be terminated at TB-1 term #9, Negative term #10. Purple and Brown wire from Micro switch is not needed on new MC521Pro.



MC521 Pro Lock Logic must be set to Fail Secure for all type locks. Actual logic is selected on the lock assembly.

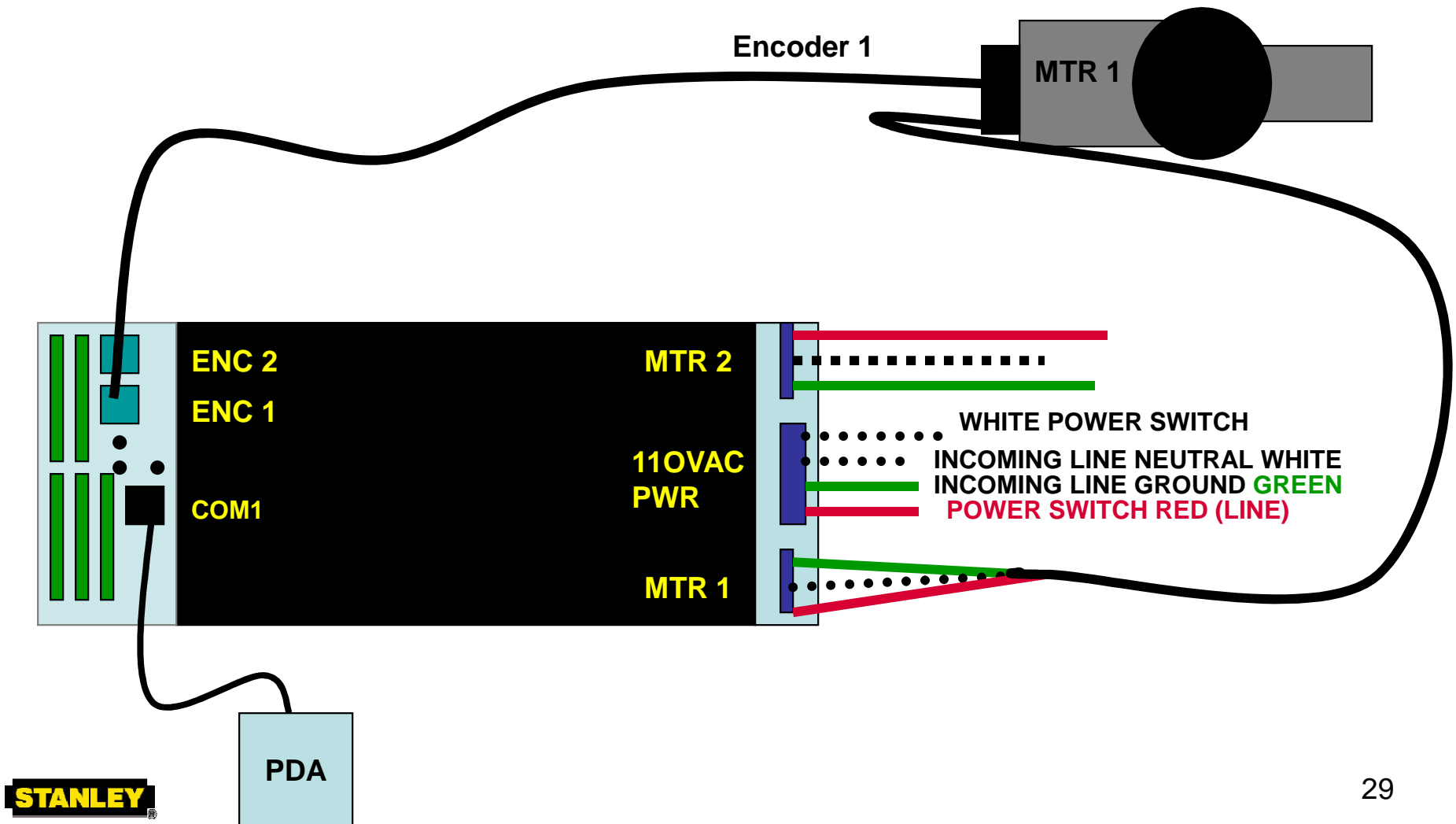


The breakout circuit on all STANLEY sliding or swinging doors is a normally closed series circuit. This circuit will open and stop the control box from electrically functioning if any switch is broken or opened by putting a door in the breakout position.



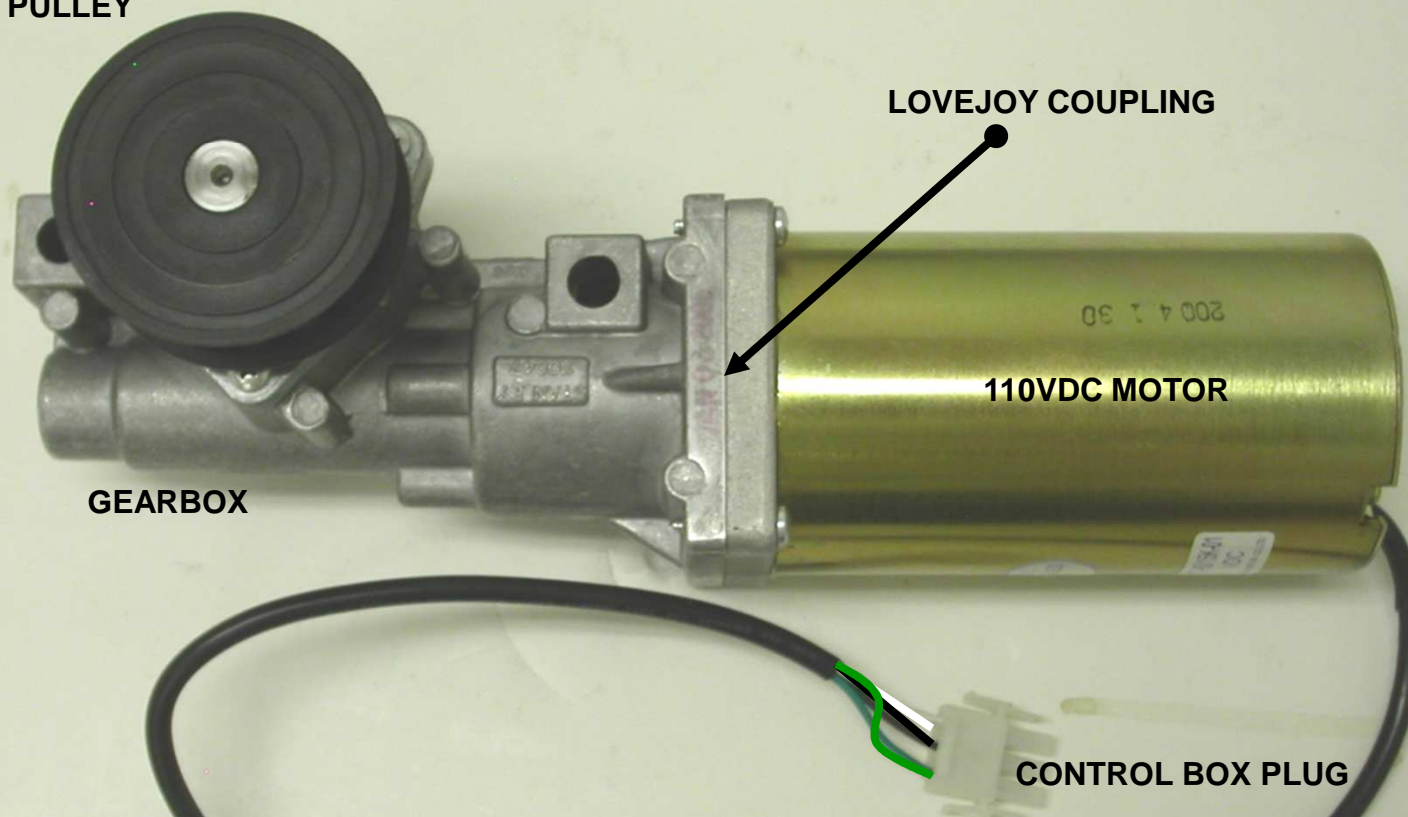
Make sure that all the sliding door panels are pushed in tightly against each other or the door will not function.

When using one or two motors on a Duraglide door, only one encoder is used. Motor 1 / Encoder 1. The slave motor (motor 2 input) if two motors are used has no encoder.

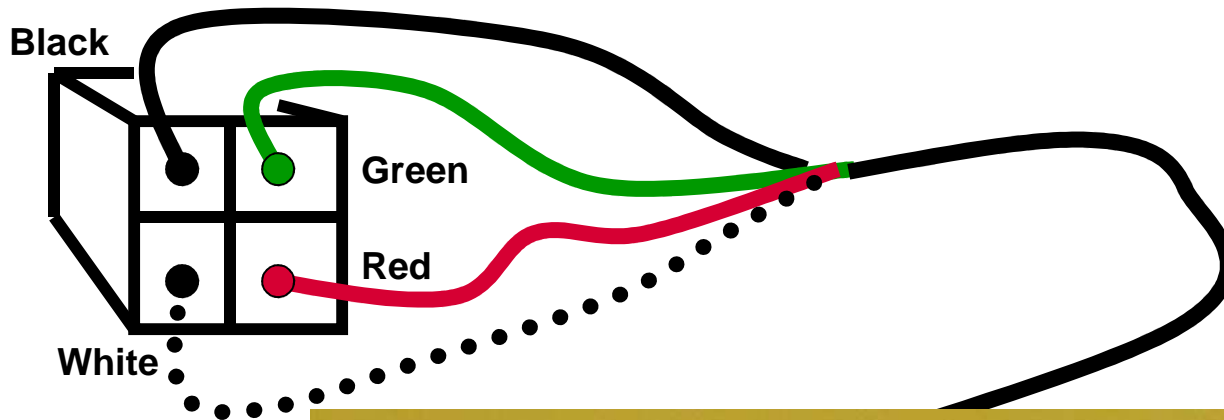


DURA-GLIDE MOTOR – GEAR BOX

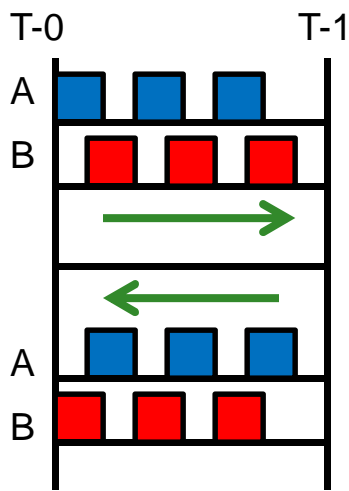
MOTOR PULLEY



To check a DC motor unplug motor plug from control, read continuity between the *black and white* wires, you should read approximately 13 ohms. You may also use insulated needle nose pliers and with the motor plug unplugged short the black and white wires and move the door, you should feel heavy resistance to door movement open or close & should be smooth not jerky.



Two Channel Encoder (A/B)

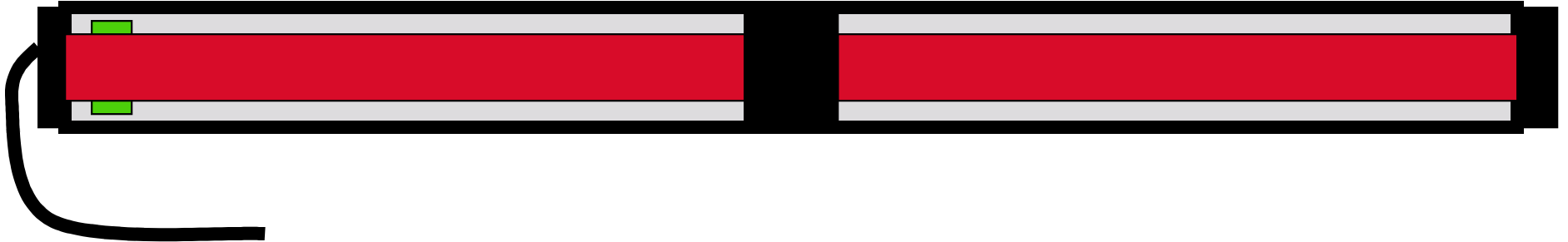


MC521 / MC521PRO ENCODER



STANGUARD PRESENCE SENSOR

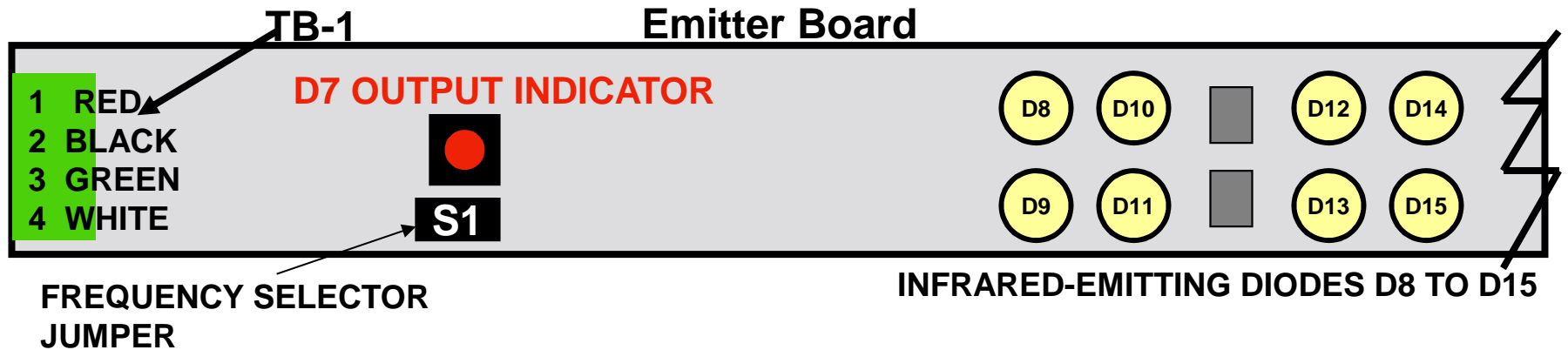
Under ANSI 156.10-2005 Dual safety beams must be installed with Stanguard sensing systems on sliding automatic door applications



A programmable active infrared (IR) presence sensing device.

- a. A built in minimum 1.5 second hold open delay.
- b. Automatic retuning. The sensor will automatically maintain its calibration and makes changes to its reference settings. If the sensor sits overnight or for long periods of time it may need to reinitialize.
- c. Frequency shifting whenever two sensors are in close proximity or on the same door a jumper can be installed to eliminate interference between the two.
- d. Zone width selection from narrow to wide openings.
- e. Detection sensitivity from normal to high for taller openings.
- f. Infrared receiver gain control. A potentiometer is provided to increase or decrease the IR receiver sensitivity.

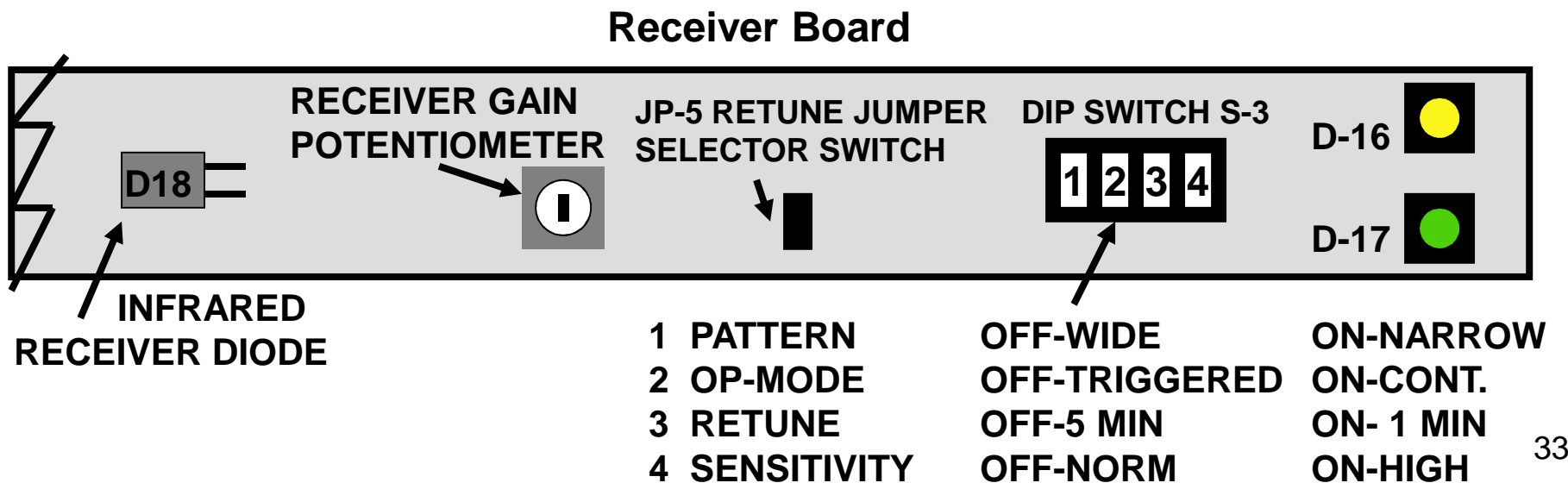
STANLEY[®]



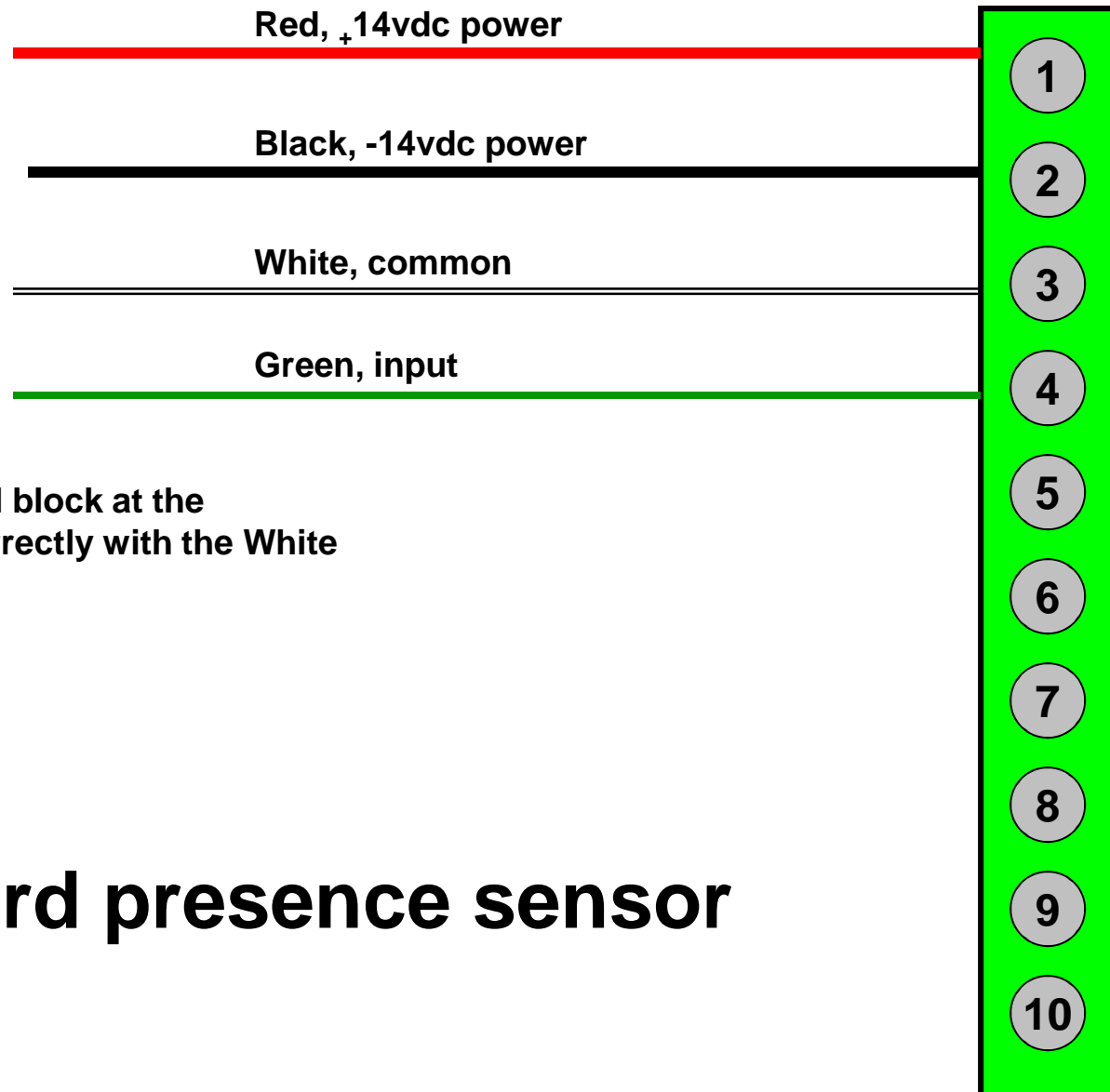
D-7 OFF an activation signal is being sent to the door, ON no activation signal.

D-16 Indicates level of reflected light being received by the receiver diode. Yellow led may flash when the door is in the closed position.

D-17 Green OFF, no detection, Green ON, detection, Green FLASHING, retuning when door is closed the Green led should be on.



TB-3



Make sure that the terminal block at the Stanguard unit is wired correctly with the White and Green wires inverted.

- TB-1 Red
- TB-2 Black
- TB-3 Green
- TB-4 White

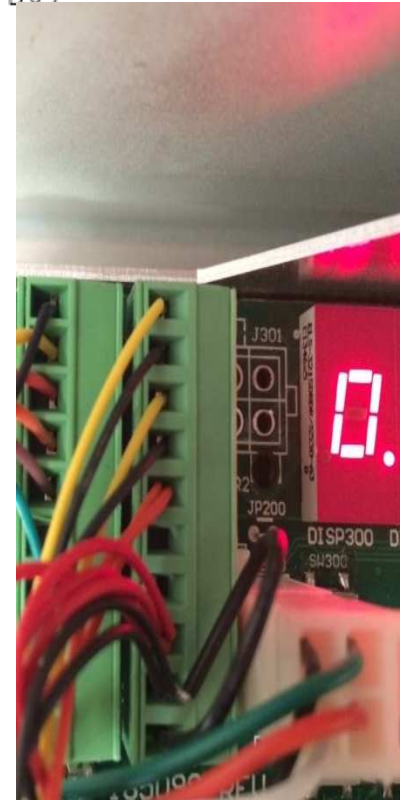
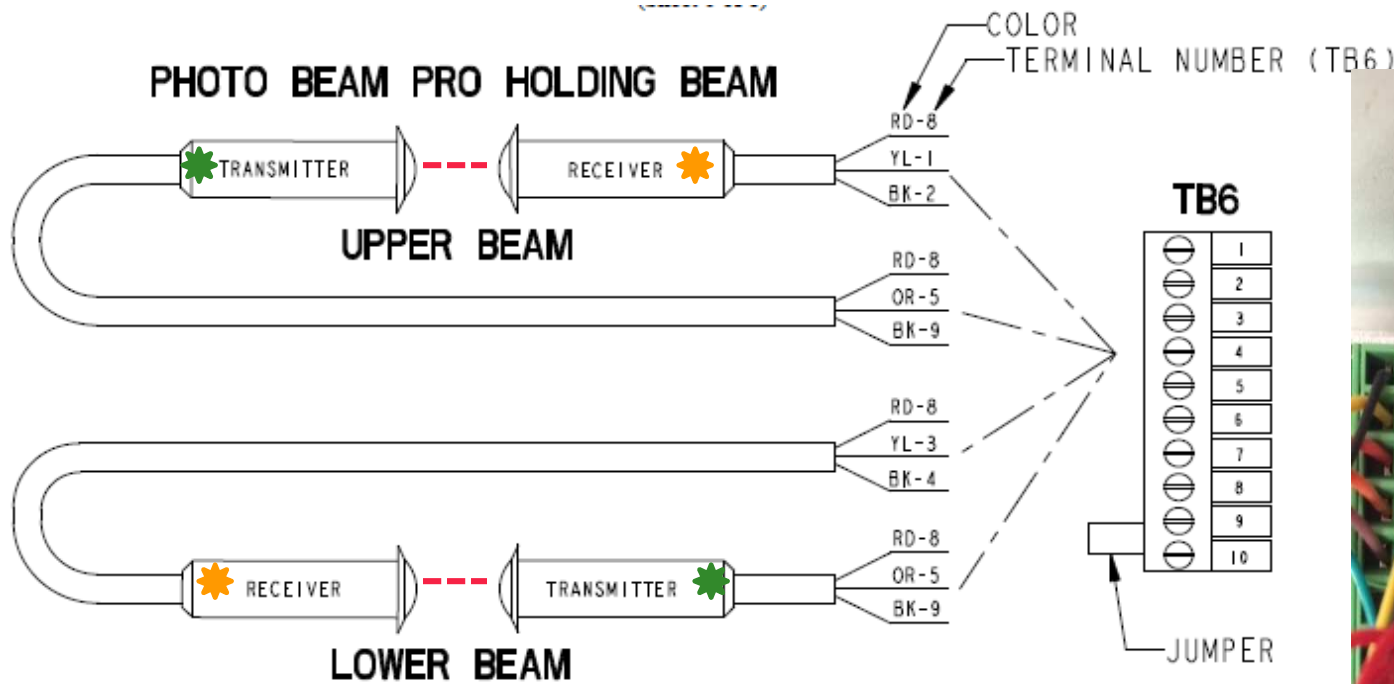
Stanguard presence sensor

521Pro Safety Beams

NOTE: During FIS safety beam type defaults to Pro Beams

--- NOTE: When IR barrier is established

- ★ Green LED on Transmitter
- ★ Amber LED on Receiver



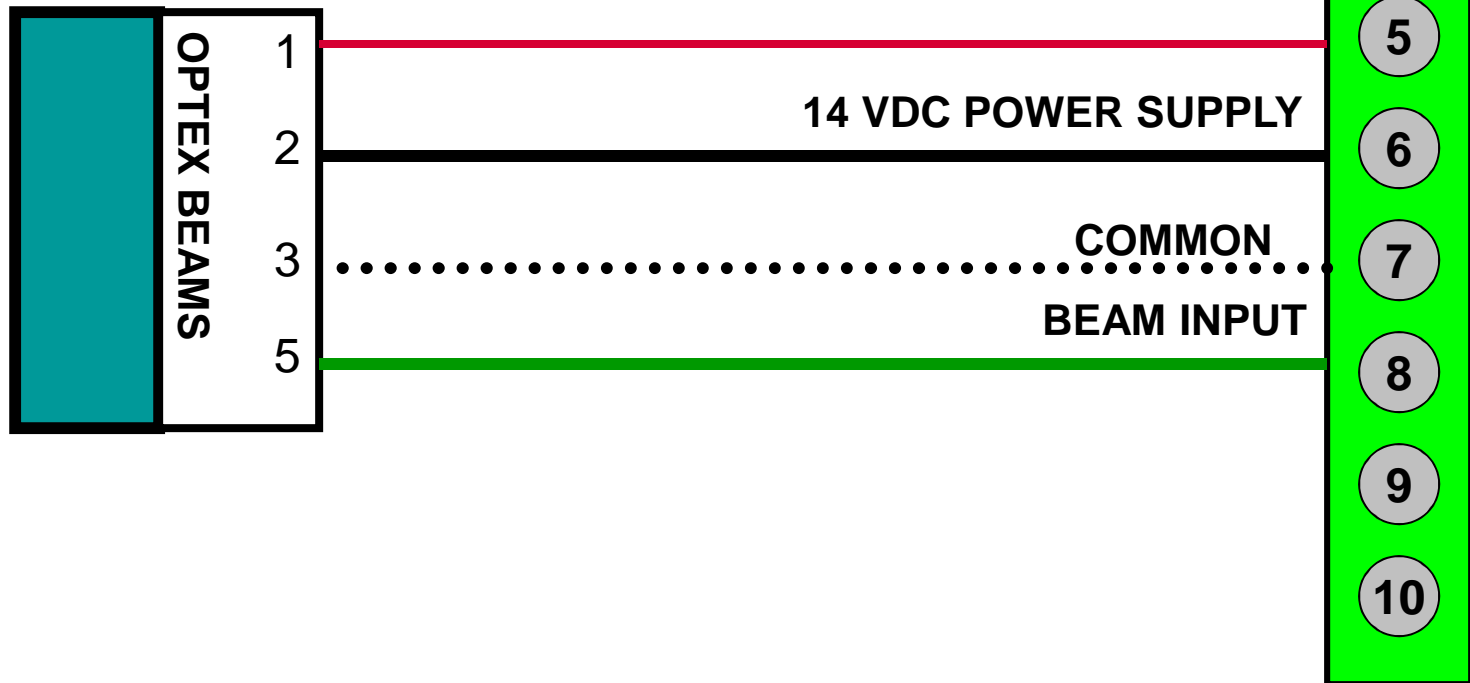
TB6	COLOR	DUAL HOLDING BEAM WIRING
1	YL	OUTPUT UPPER RECEIVER
2	BK	(-) UPPER RECEIVER
3	YL	OUTPUT LOWER RECEIVER
4	BK	(-) LOWER RECEIVER
5	OR	TRANSMITTER CONTROL LOWER AND UPPER
6	--	NO CONNECTION
7	--	NO CONNECTION
8	RD	(+) ALL RECEIVERS AND TRANSMITTERS
9	BK	(-) LOWER AND UPPER TRANSMITTERS, JUMPER TO TB6-10
10	BK	JUMPER FROM TB6-9

OPTEX Holding Beam Input

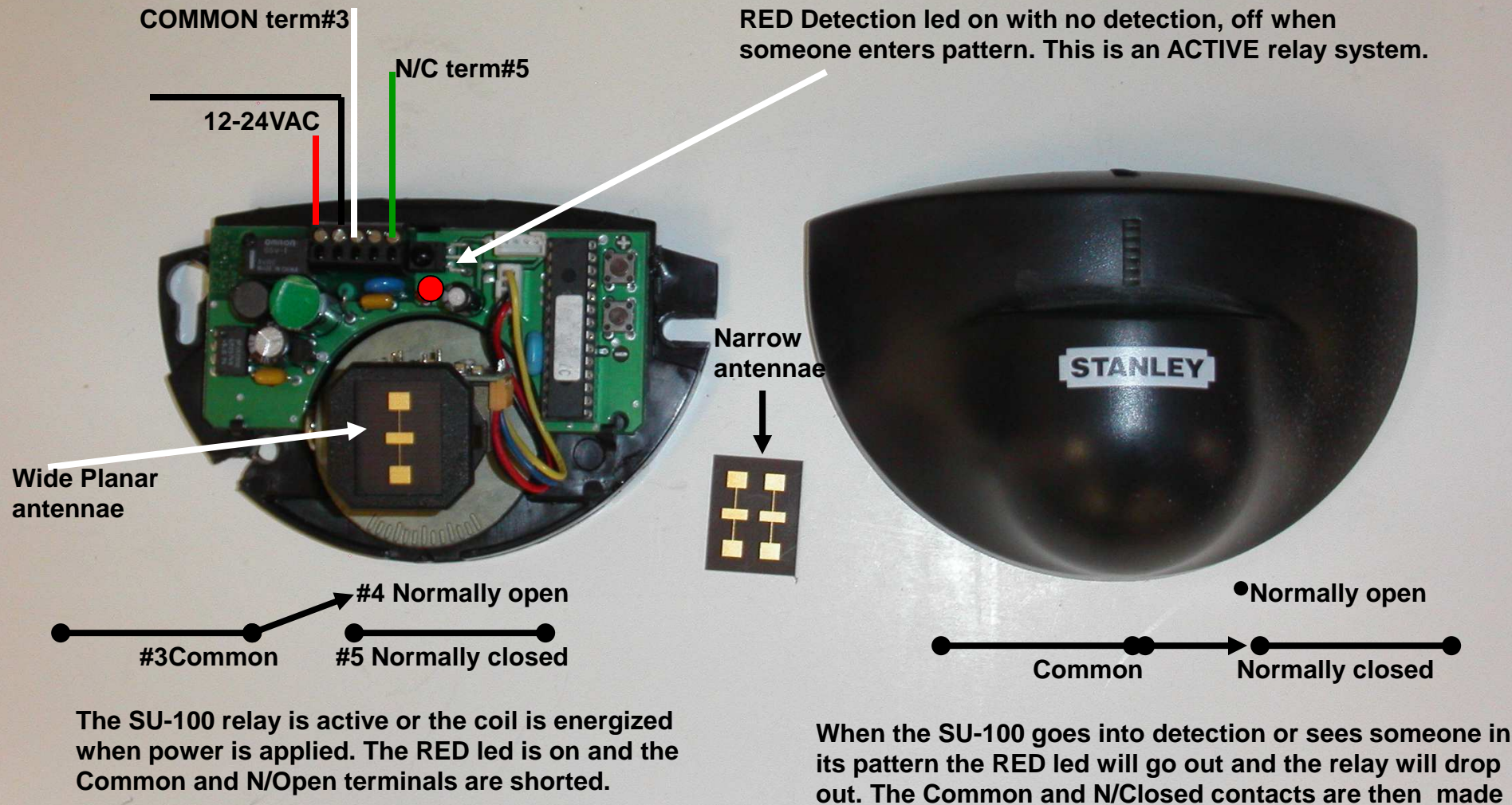
TB-3

NOTE: After FIS must set beam type to OPTEX

OS-12 Controller



STANLEY SU-100 MOTION SENSOR

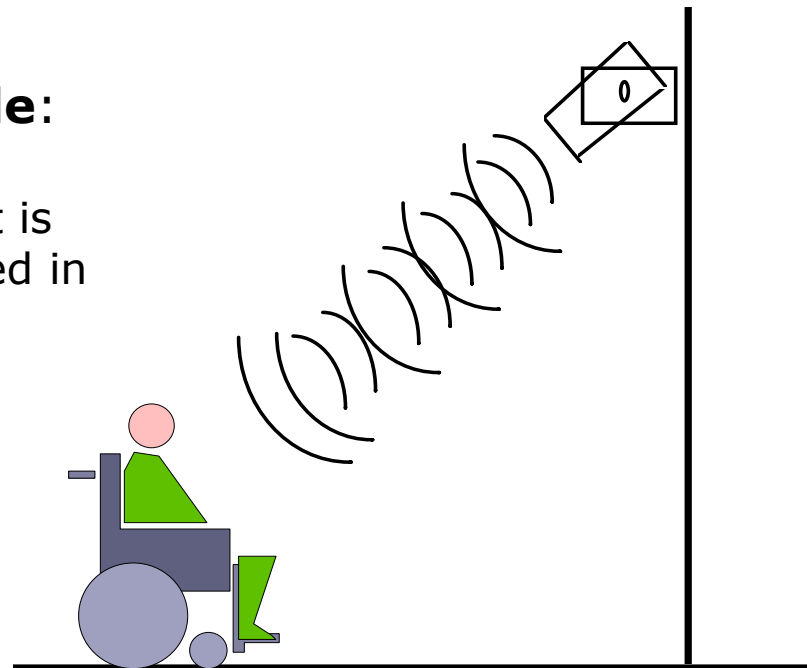


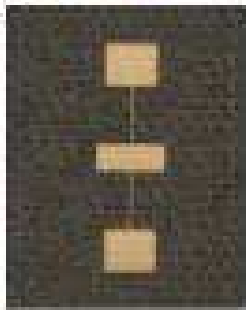
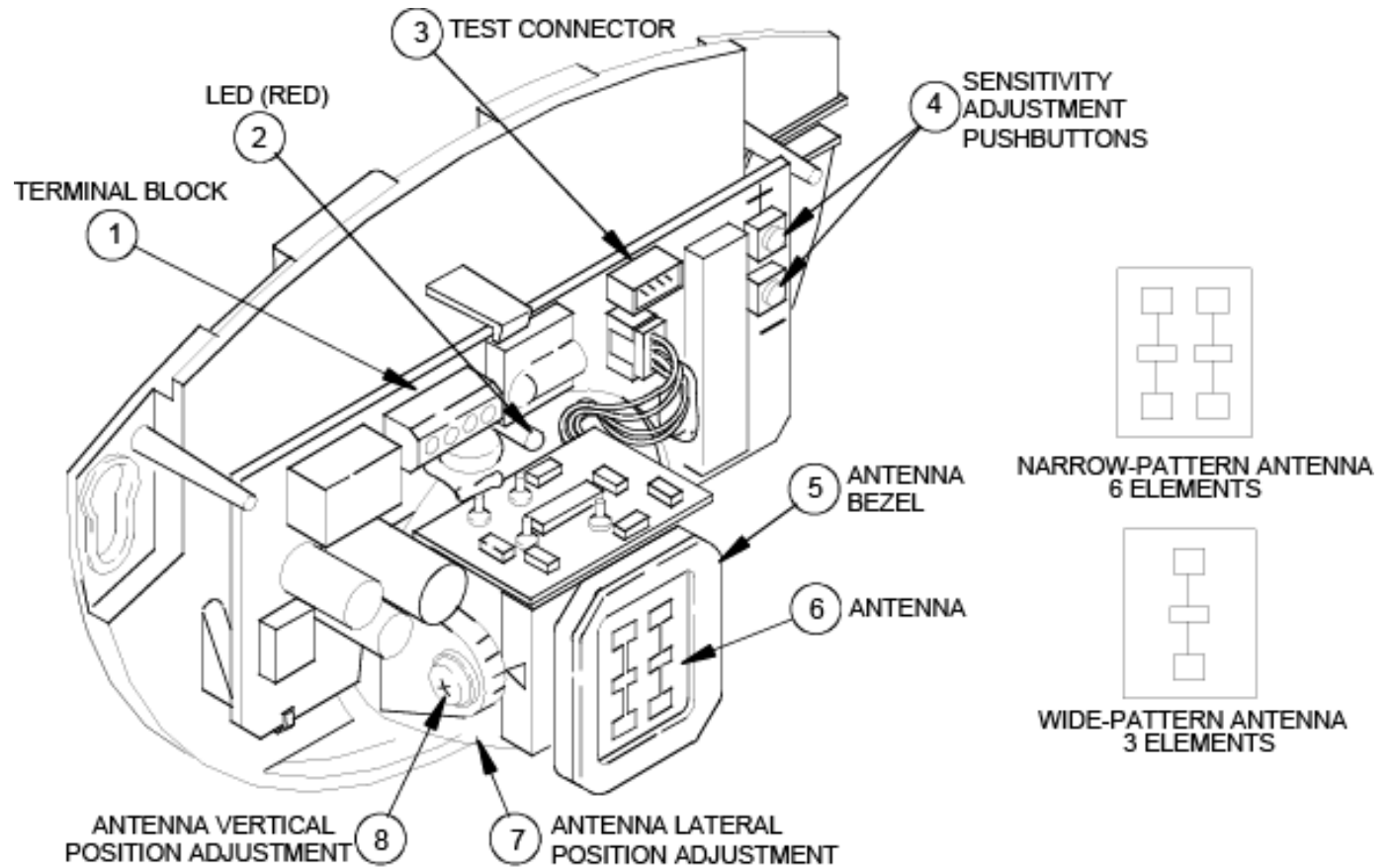
SU-100 Active relay Mode

- The SU-100 is power up. But with No Detection The Relay is ACTIVE in the NORMALLY/OPEN State.
- Power is removed from the relay coil during detection
- During detection, the Relay is Passive, coil not energized) the led is off and the relay is NORMALLY/CLOSED
- During a Sensor Failure, The Relay contacts will be CLOSED and an activation signal will be sent to the control.

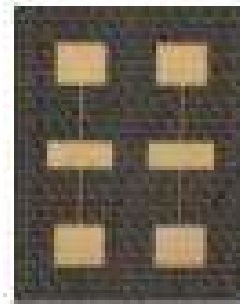
Based on Doppler Effect Principle:

When a radar strikes a moving object, it is reflected back and its frequency is shifted in proportion to the speed of the object.

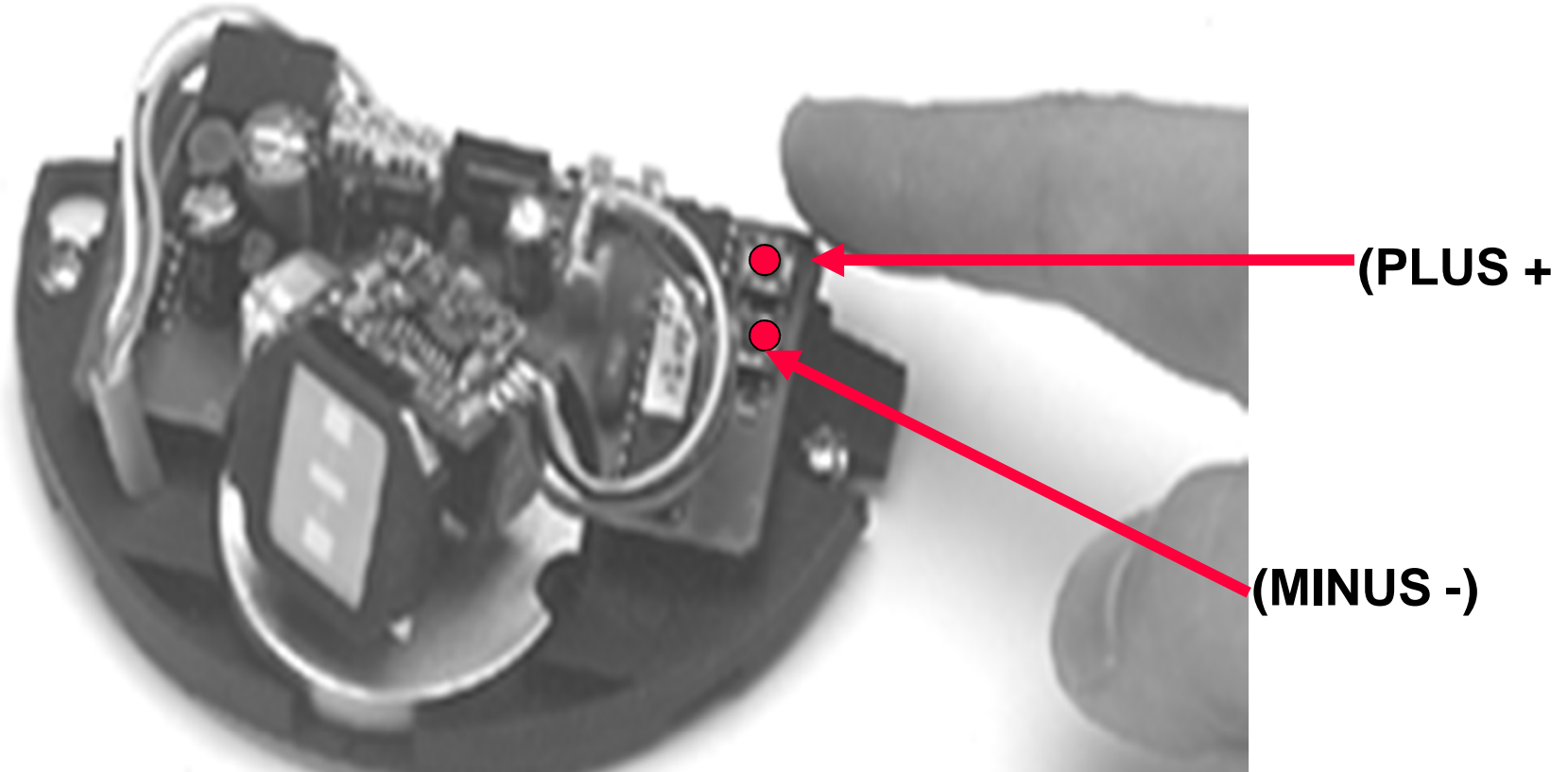




Wide antenna



Narrow antenna



If a remote control is not available, you can adjust the sensitivity parameter ONLY, by means of the push buttons + (Plus) and - (Minus).

TB-4

Red, power +

Black, power -

White, common

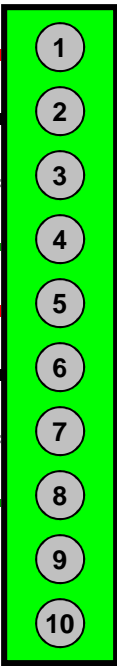
Green, input

Red, power +

Black, power -

White, common

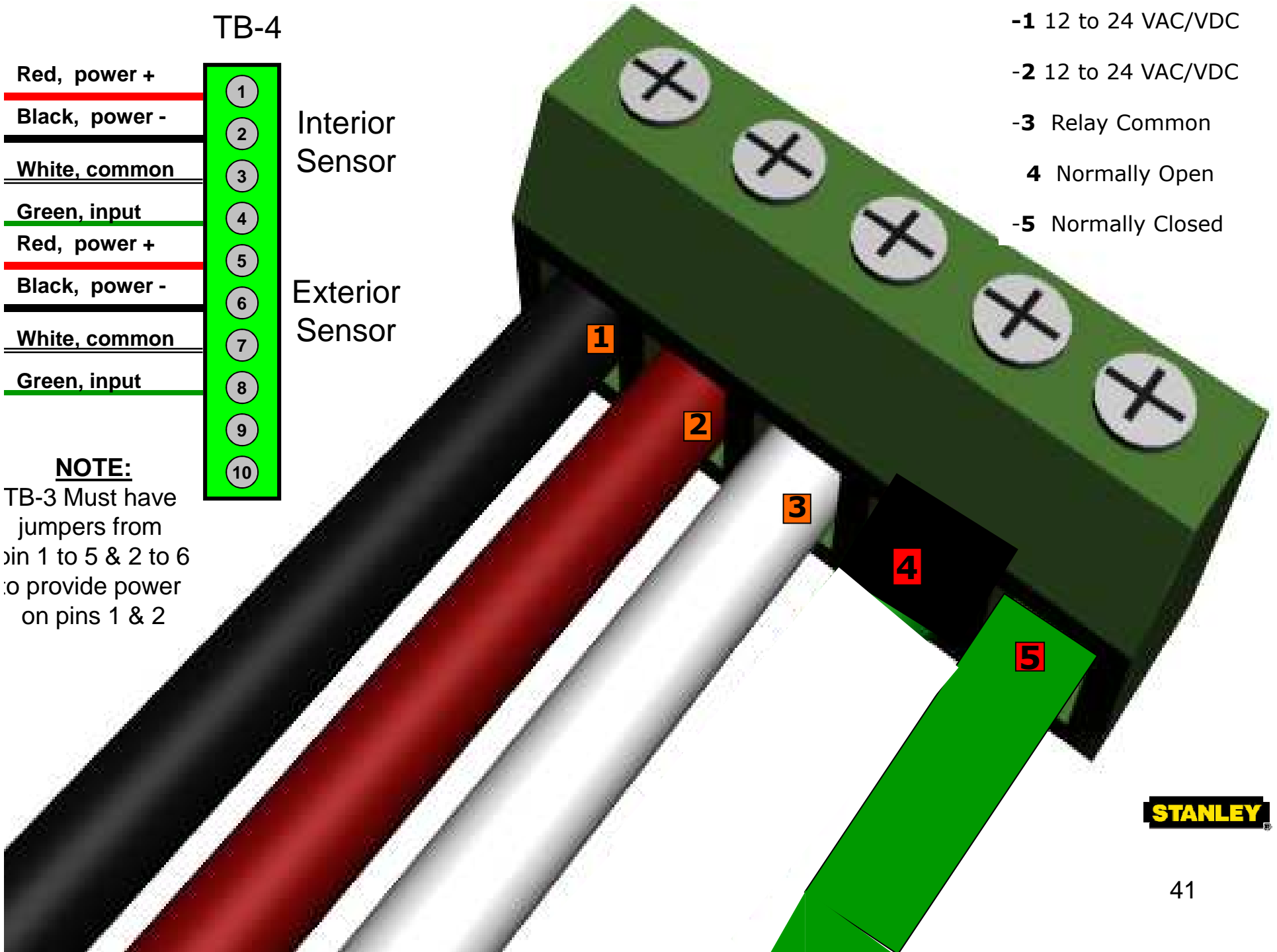
Green, input



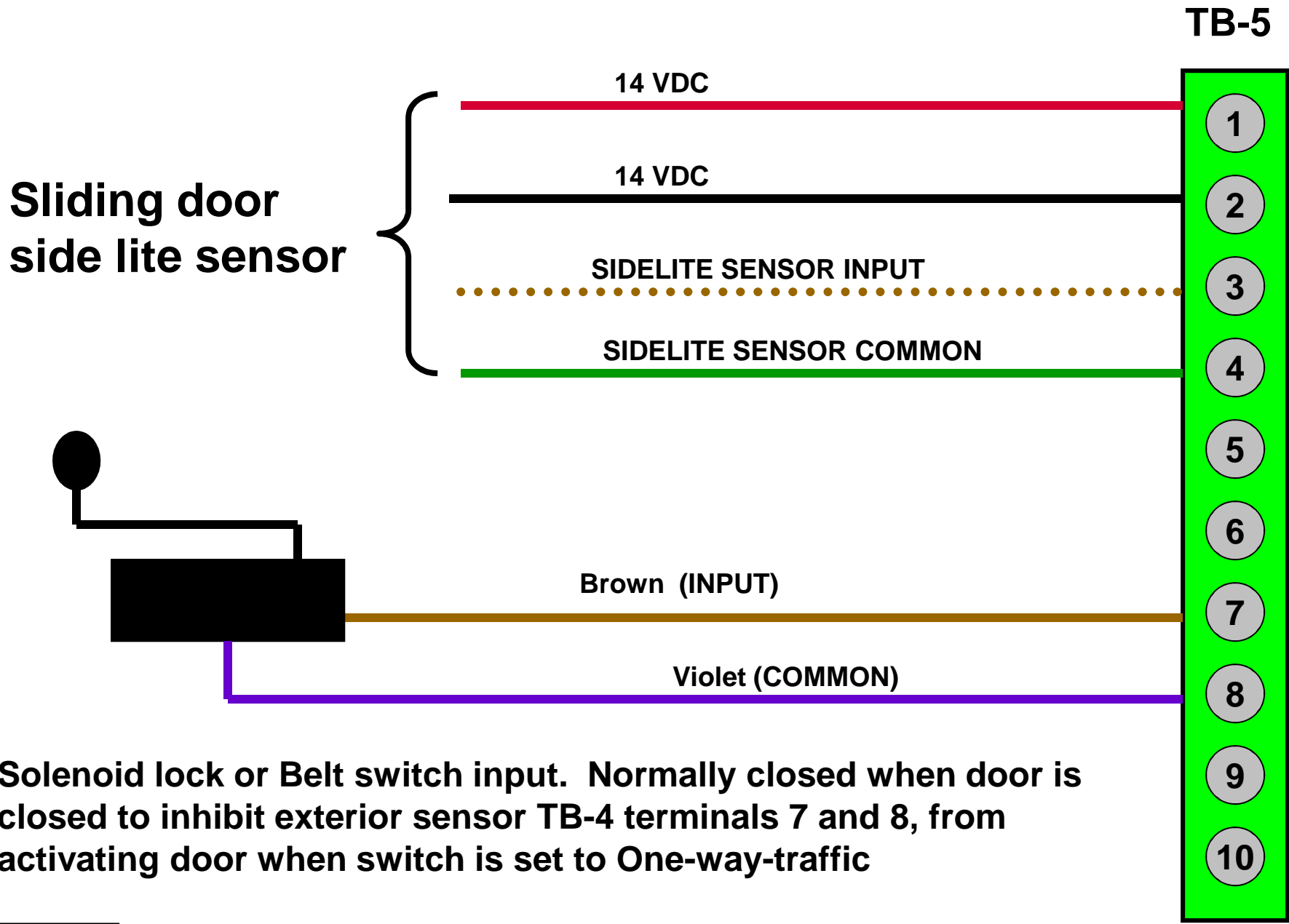
Interior Sensor

Exterior Sensor

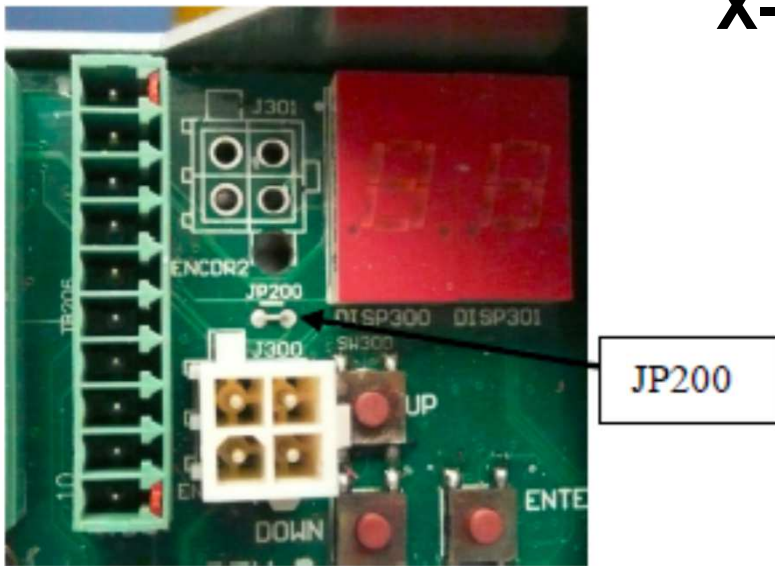
NOTE:
TB-3 Must have jumpers from pin 1 to 5 & 2 to 6 to provide power on pins 1 & 2



- 1 12 to 24 VAC/VDC
- 2 12 to 24 VAC/VDC
- 3 Relay Common
- 4 Normally Open
- 5 Normally Closed



X-Zone-T Monitor Capable Sensor



When enabling monitoring for X-Zone T, the control box needs to be configured.

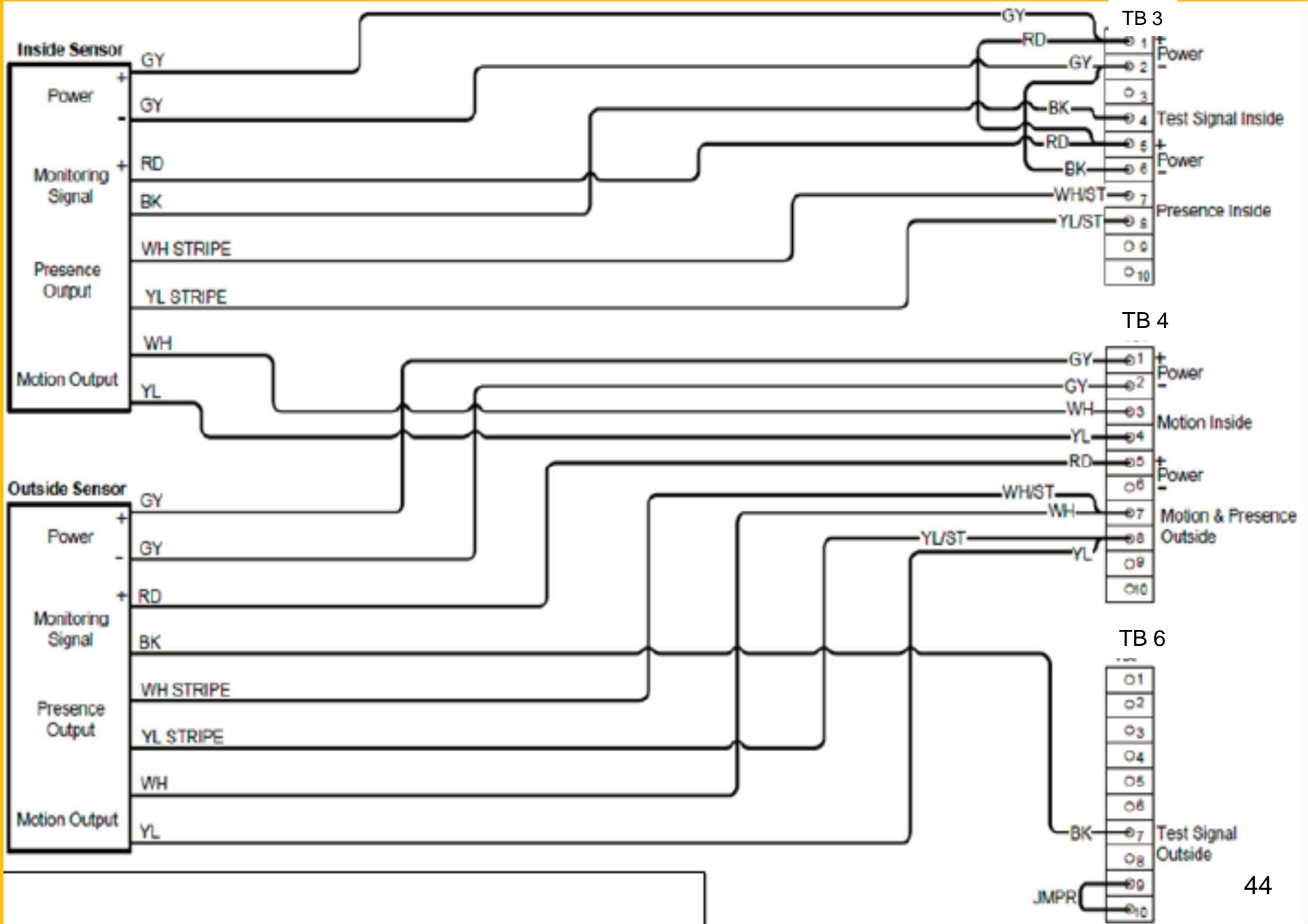
1. Clip the JP200 jumper wire on the MC521 Pro, located between the two Encoder connectors.

NOTE: AFTER JP200 IS REMOVED, THIS CONTROL BOX CANNOT BE USED WITH A STANGUARD SENSOR.

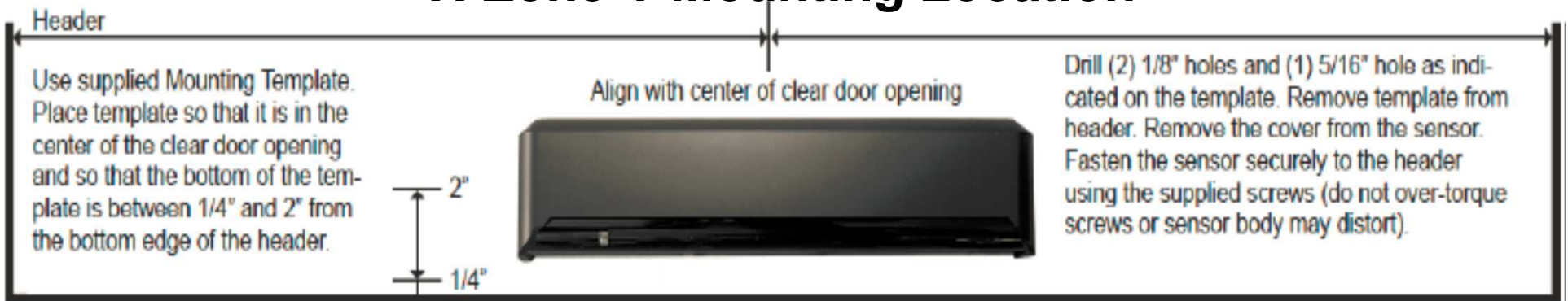
The JP200 jumper is an internal MC521 Pro connection that enables TB3-4 to be used as an input and output required for StanGuard.

2. Enable Monitoring:
 - A. Using push buttons on control set Index 19 = Value 03.
 - B. Using BT dongle and MC-521 Toolbox application set function Safety Logic = Monitored Sensors.

X-Zone-T wiring to MC-521 Pro



X-Zone-T Mounting Location



For ease of wiring recommend mounting height 2" from bottom of header to bottom of template.

Exception - Duramax 5400

Cover side of predrilled for mounting. If no prep then place template 1/4" up from bottom of cover. On Non cover side place template 1/4" up from bottom of header. Drill a 1/2" diameter wire access hole in location as shown below.



X-Zone-T Settings

Remove the cover and unfold the label.



1. Dipswitch settings

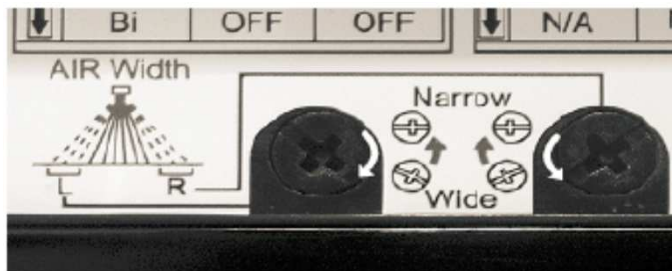


NOTE: If uni-directional motion detection is desired, move dipswitches 9 UP.
Refer to instruction manual for details on all dipswitch settings.

Start with dipswitch settings shown upper right. Dipswitch 12 MUST be DOWN & 13 MUST be UP. All dipswitch functions are listed on the label.

Dipswitches labeled in RED only affect Presence/AIR.

Dipswitches labeled in Blue only affect Motion/Microwave.



Adjust Presence/AIR area width with shutters
Left & right area can be set independently
At standard height (89" A.F.F.):
Wide = Approx. 8.5 feet wide
Narrow = Approx. 4.25 feet wide

To adjust the microwave detection area width, use the narrow lens as shown in the picture below.



Adjust the Motion/Microwave area width
by installing or removing the Narrow lens.
Wide = Approx. 12.5 feet wide
Narrow = Approx. 6.25 feet wide

X-Zone-T Settings Continued

Start with the settings shown below and in most cases no other adjustment will be necessary.

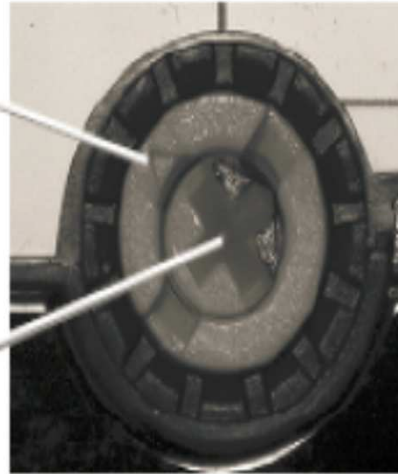
AIR (Presence) and Microwave Angle Adjustments

AIR Angle Adjust

Set Red Ring at -2 degrees
(Arrow at Approx. 10 o'clock)

Microwave Angle Adjust

Set center Philips adjuster to 38 degrees
(Blue Dots are at 2 o'clock)

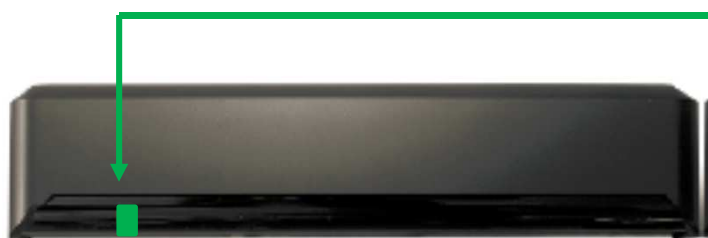


WARNING: To comply with ANSI A156.10, if the reveal on the door (mounting surface of sensor to face of sliding panel) is greater than 2½", turn the AIR adjuster (Red Ring) CCW (Shallow) until the door recycles on the closing cycle. Then refer to step 2 under troubleshooting to properly adjust the AIR angle.






4. Microwave Sensitivity



Set to 10 o'clock (two dots at top)



OPERATION L.E.D.

-  Solid Green = Standby, No Detection
-  Solid Orange = Motion/Microwave Detection
-  Solid Red = 3rd row AIR Detection
-  Flashing Red = 2nd Row AIR Detection
-  Solid Blue = 1st Row AIR Detection (Blue Zone thru Threshold)

Troubleshooting

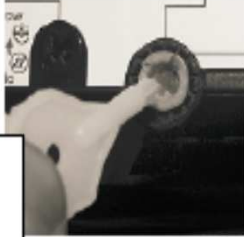
Door reopens on closing cycle:

1. Operation LED turns solid Orange then door reopens (Microwave Motion Detecting Door)

a. Reduce sensitivity: turn sensitivity potentiometer CCW.



b. Adjust Microwave angle towards deep (Clockwise) slightly.



NOTE: If recycle continues try turning Microwave Immunity ON (Dipswitch 10)

2. Operation LED turns Flashing Red, then door reopens

(Row 2 Presence Detecting Door)

a. Move AIR angle adjustment (Red Ring) slightly Clockwise until ghosting stops.



NOTE: When changing the AIR angle, sensor may go into detection and hold door open. In this case, reset sensor by moving any dip-switch, then move it back.

Door remains open, MC-521 Pro Displays F.0. or F.1. (F.0.=Inside sensor, F.1. = Outside Sensor):

- Verify sensor presence wires (White/Stripe & Yellow/Stripe) properly connected to control.

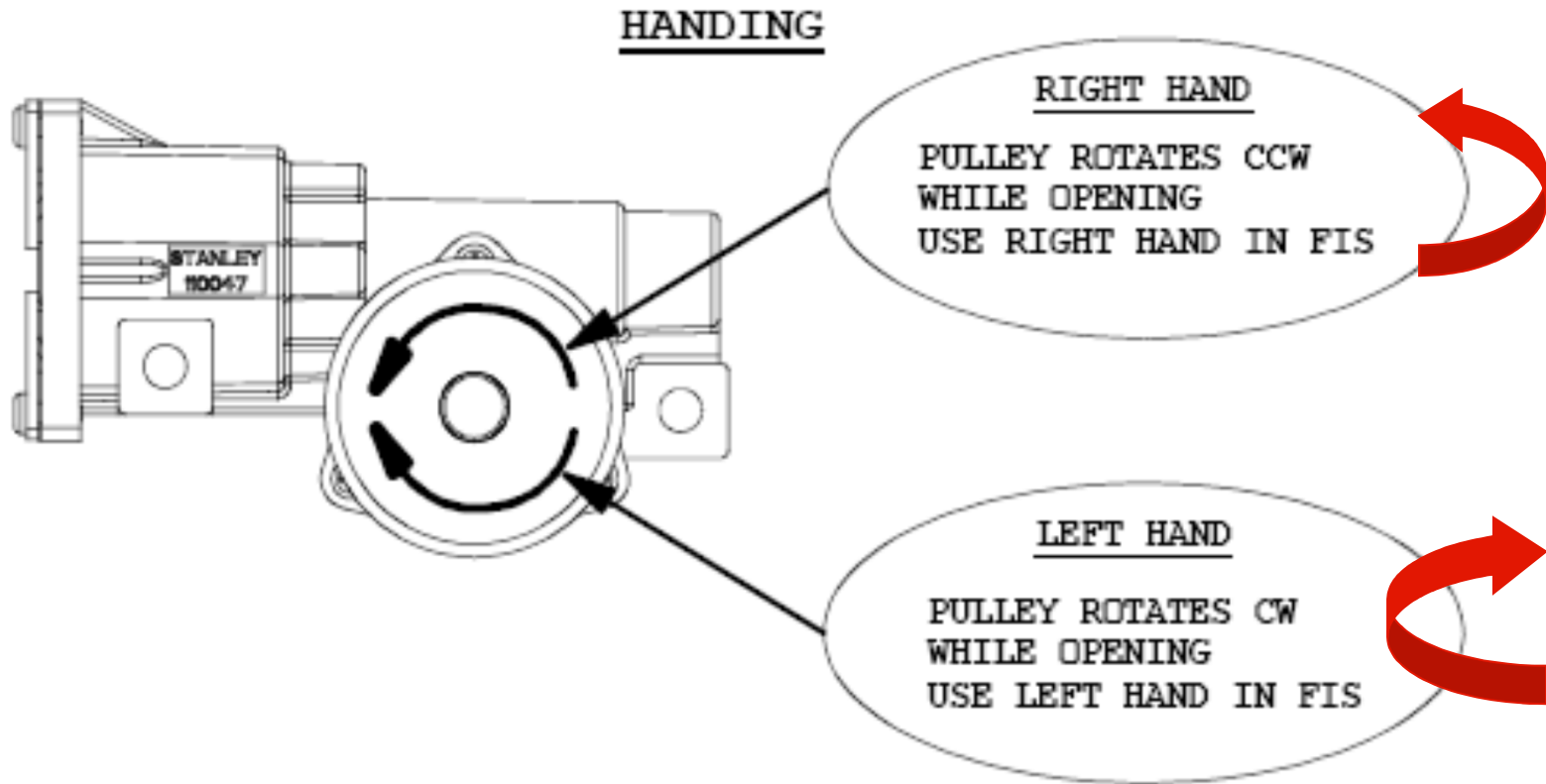
Door remains open, MC-521 Pro Displays 0.6. / h.o. alternately:

- Verify Black Wire & Red wire from Sensor connected properly at control.

Verify sensor dipswitch 12 set Down & 13 set UP.

Sliding Door Handing

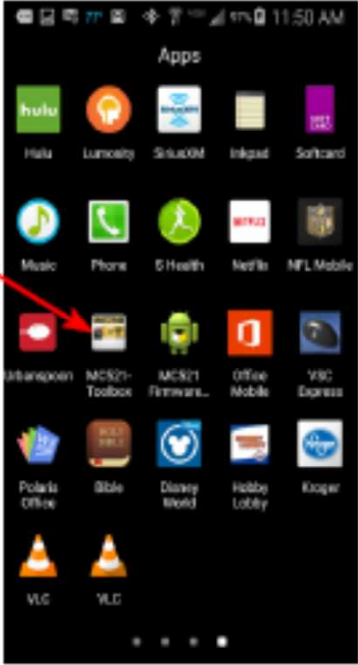
For the Purpose of FIS Only




NOTE: For Bi-part set to Right Hand and ensure Tall Belt Bracket is installed on Left SX Panel (as viewed from header cover side).

FIS with BT Dongle and MC-521 Toolbox

NOTE: Door Mode switch must be set to Closed Locked Position



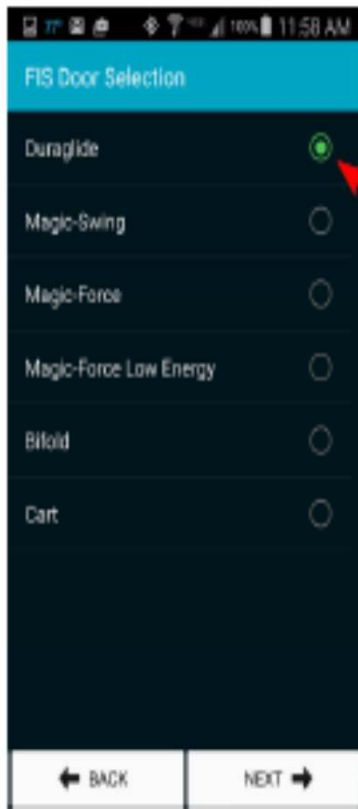
Step 1: Select MC521 Toolbox from the list of applications.



Step 2: Select **RESTART FIS** on the Main selection menu. (FIS = First Install Sequence).

NOTE: Firmware is the software revision. Cycles are door cycles in memory.

FIS with BT Dongle and MC-521 Toolbox (Cont.)



3

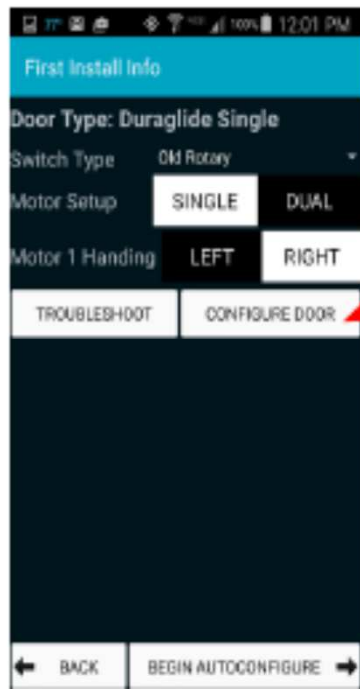
Step 3: Select Duraglide.



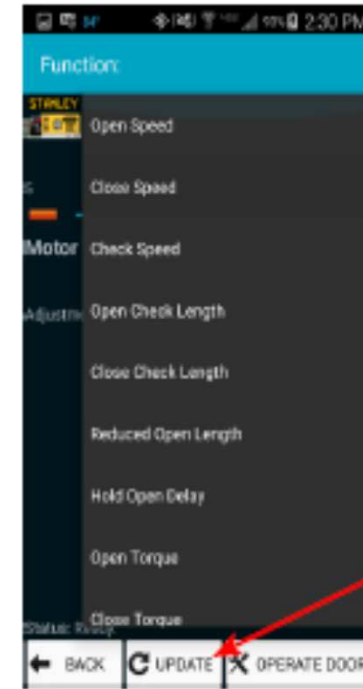
4

Step 4: Select applicable Switch Type, Motor Setup, and Motor Handing.

FIS with BT Dongle and MC-521 Toolbox (Cont.)



Step 5: If additional configuration is needed, press **CONFIGURE DOOR**.



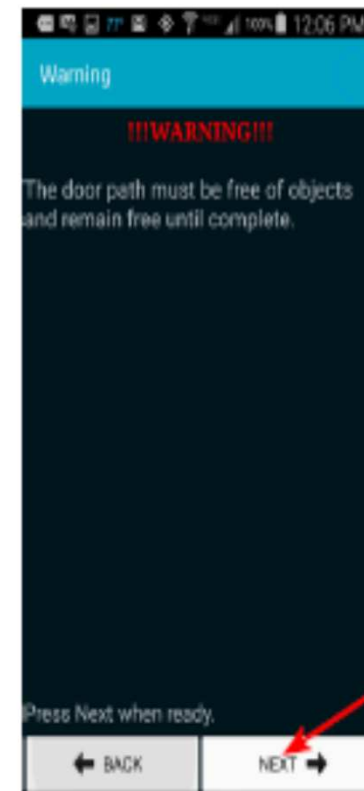
Step 6: Configure additional settings and press **UPDATE** after each setting has been changed. Once completed, press **BACK** to go back to the Main selection menu.

FIS with BT Dongle and MC-521 Toolbox (Cont.)

NOTE: If using Rotary Switch ensure “Old Rotary” is display at “Switch Type” before selecting “BEGIN AUTOCONFIGURE”.

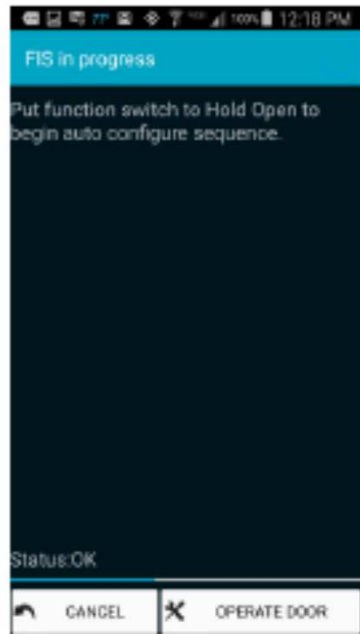


Step 7: Press **BEGIN AUTOCONFIGURE**.



Step 8: Press **NEXT**.

FIS with BT Dongle and MC-521 Toolbox (Cont.)

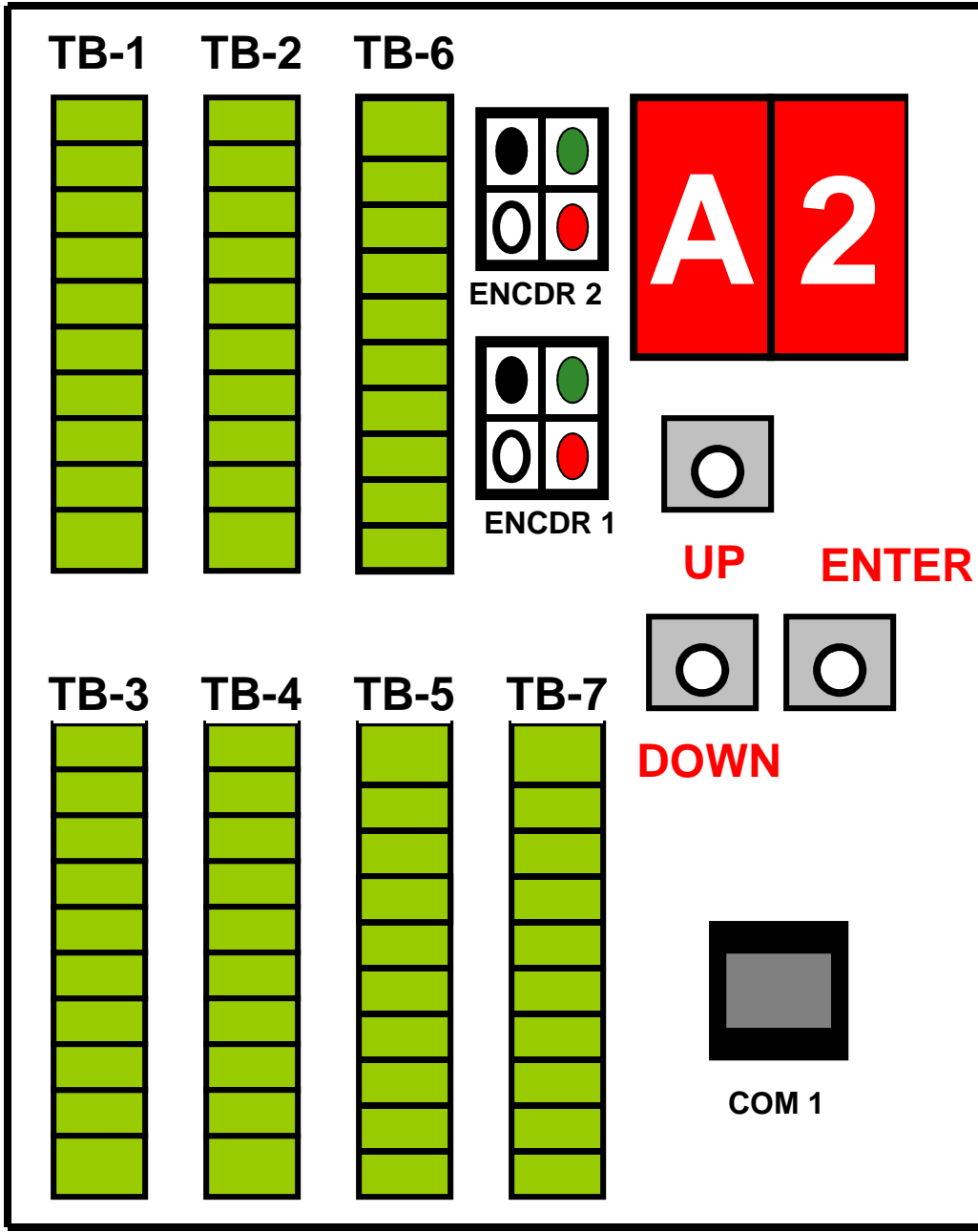


Step 9: Put door function switch to **Hold Open** then immediately back to **Closed**. The same function can be done remotely from the Palm by pressing **Operate**.

WARNING: During this sequence the sensors are inactive and the door has no **SAFETY**. To stop the door, **TURN POWER OFF** or **PUT THE DOORS INTO BREAKOUT**.

Step 10 Door will go through a learn sequence to configure itself. The door will perform the following operations in learn mode:

- Open fully at check speed.
- Close fully at check speed.



To change an (index) you must hold the ENTER button down while moving the UP and DOWN to find the correct index number.

Once you have found the correct index you release the ENTER button and immediately scroll up or down to change the value of that INDEX.

Once you have stopped scrolling up or down the value number will flash and then display the STATUS.



Table 1. FIS (First install sequence) procedure using pushbuttons

STEP#1	Set function switch to "CLOSED"	INDEX	VALUE	STATUS
STEP#2	Turn power ON			
STEP#3	Unlock Keypad	99	00	00
STEP#4	Restart FIS	96	01	A0
STEP#5	Select door type Dura-glide (motor)	00	01 (single) 02 (dual)	A0
STEP#6	Select door handing.	01	00 (right) 01 (left)	A0
STEP#7	Accept FIS. Display with go to A1	03	01	A1
STEP#8	Make changes: Function switch type	11	01 (rocker) 00 (rotary)	A1
STEP#9	Select Lock Logic	07	00 (fail safe) 01 (fail secure)	

STEP#10 WARNING; Sensors and safety inactive during this sequence, to stop the door turn the power off or put the doors into BREAK-OUT!. Put function switch to Hold-Open and then back to OFF. Door should open to stops and close, the display will show A2.

STEP#11 Lock the keypad 99 01 00₅₆

MAKE SURE DOOR IS IN COMPLIANCE WITH ANSI 156.10 - 2011

x	Min. Value	Max. Value	Description	Defaults	
				Single	Dual
	05	35	Open speed, increment by 1.	25	25
	05	18	Close speed, revolutions per second.	12	12
	03	10	Check speed, revolutions per second.	04	04
	10	99	Open check length, percent of full opening.	35	35
	10	99	Close check length, percent of full opening.	30	30
	00	99	Reduced open position, percent of full opening (00=full open, 99=full close).	50	50
	01	99	Hold open delay (0 to 25 sec.).	03	03
	01	03	Lock Logic, 00 = Fail Safe, 01 = Fail Secure, 02 = Dura-Max Fail Safe, 03 = Dura-Max Fail Secure Note: For locks with circuit board, set to 01 Fail Secure. For locks with no circuit board, set to Fail Safe or Fail Secure.	01	01
	00	75	Open torque, percent of full scale.	25	25
	00	75	Close torque, percent of full scale.	25	15
	00	75	Check torque, percent of full scale.	25	10
	00	01	Dura-Glide function switch type: 00=double pole rotary, 01=rocker	01	01
	00	01	2S Operation, 0=off, 1=on	00	00
	01	60	Obstruction Time Delay (.01 - 1.5 sec) Heavy and dual motor doors may require a longer obstruction time (45 on buttons or 1.2 sec. on Palm).	20	40
	20	60	Open Acceleration, (larger value=faster acceleration).	50	50
	20	60	Open Braking, (larger value=increased braking). 20=No open braking	54	54
	20	60	Close Acceleration, (larger value=faster acceleration).	20	20
	20	60	Close Braking, (larger value=increased braking). 20=No close braking	40	40
	00	02	00 = Off (Delay Egress), 01 = 15 sec. delay, 02 = 30 sec. delay	00	00
	00	04	Safety Logic, Do Not Change. Must be set to 04.	04	04
	00	01	Hold Beam Type 00 = Optex, 01 = Photo Beam Pro	01	01
	01	50	Lock Delay (0.1 - 5.0 sec)	01	01
	00	64	Open Stop Distance (1/8" increments) from full open the door will stop.	04	04
	00	01	Access Control Pro 00 = off, 01 = on	00	00
	00	03	Press Time, 00 = least amount, 03 = most amount of pressing After obstruction timeout, the number of seconds the door presses at Full Closed	01	01

x : Door must be cycled open for changes to be stored in permanent memory.

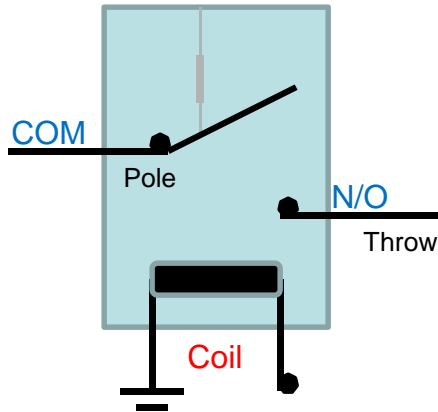
t currently available on Palm

Table 4. Status Codes

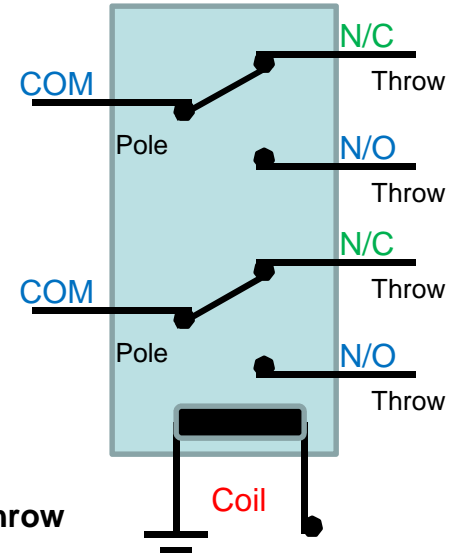
Status Code	Description	Remediation IF necessary
00	Normal operation—All OK	
0b	Obstruction	
20	Breakout	
33	System error	1. Reset Power 2. If code does not clear, Call Tech Support
A0	First installation sequence (FIS)	
A1	Auto-configuration sequence	
A2	Auto-configuration confirmation sequence	
b1	Encoder error	
Ld	Lock Down (Shear Lock Energized)	
dc	Display door cycle counter	
dE	Delayed Egress	
d0	Shear Lock De-Energized	
E1	Upper hold beam sensor error	Verify sensor wiring and safety logic setting
E3	Door length error	Re-do first installation sequence (FIS)
E4	Safety sensor error	Verify sensor wiring and safety logic setting
E5	Inside activation sensor error	Verify sensor wiring and safety logic setting
E6	Outside activation sensor error	Verify sensor wiring and safety logic setting
E7	Lower hold beam sensor error	Verify sensor wiring and safety logic setting
E8	Inside presence sensor error	Verify sensor wiring and safety logic setting
E9	Outside presence sensor error	Verify sensor wiring and safety logic setting
F0	Inside Active8 sensor failure	Verify sensor wiring and safety logic setting
F1	Outside Active8 sensor failure	Verify sensor wiring and safety logic setting
F2	Upper Photo Beam Pro sensor failure	Check transmitter, receiver, and hold beam type
F3	Lower Photo Beam Pro sensor failure	Check transmitter, receiver, and hold beam type
ho	Door held open	Check sensors and hold beam type

Relay Terminology / Logic

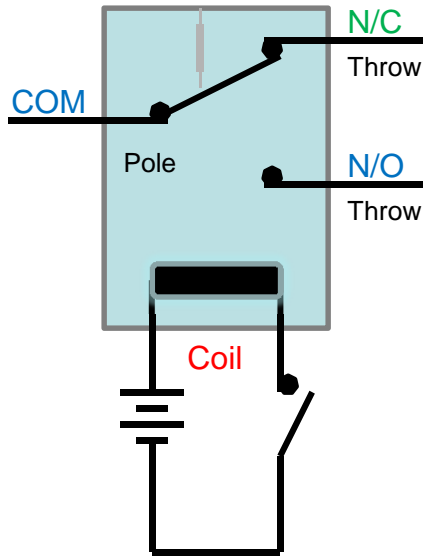
Single Pole Single Throw
S.P.S.T.



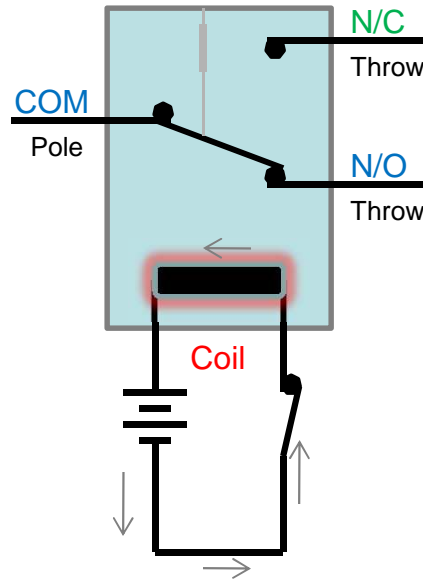
Double Pole Double Throw
D.P.D.T.



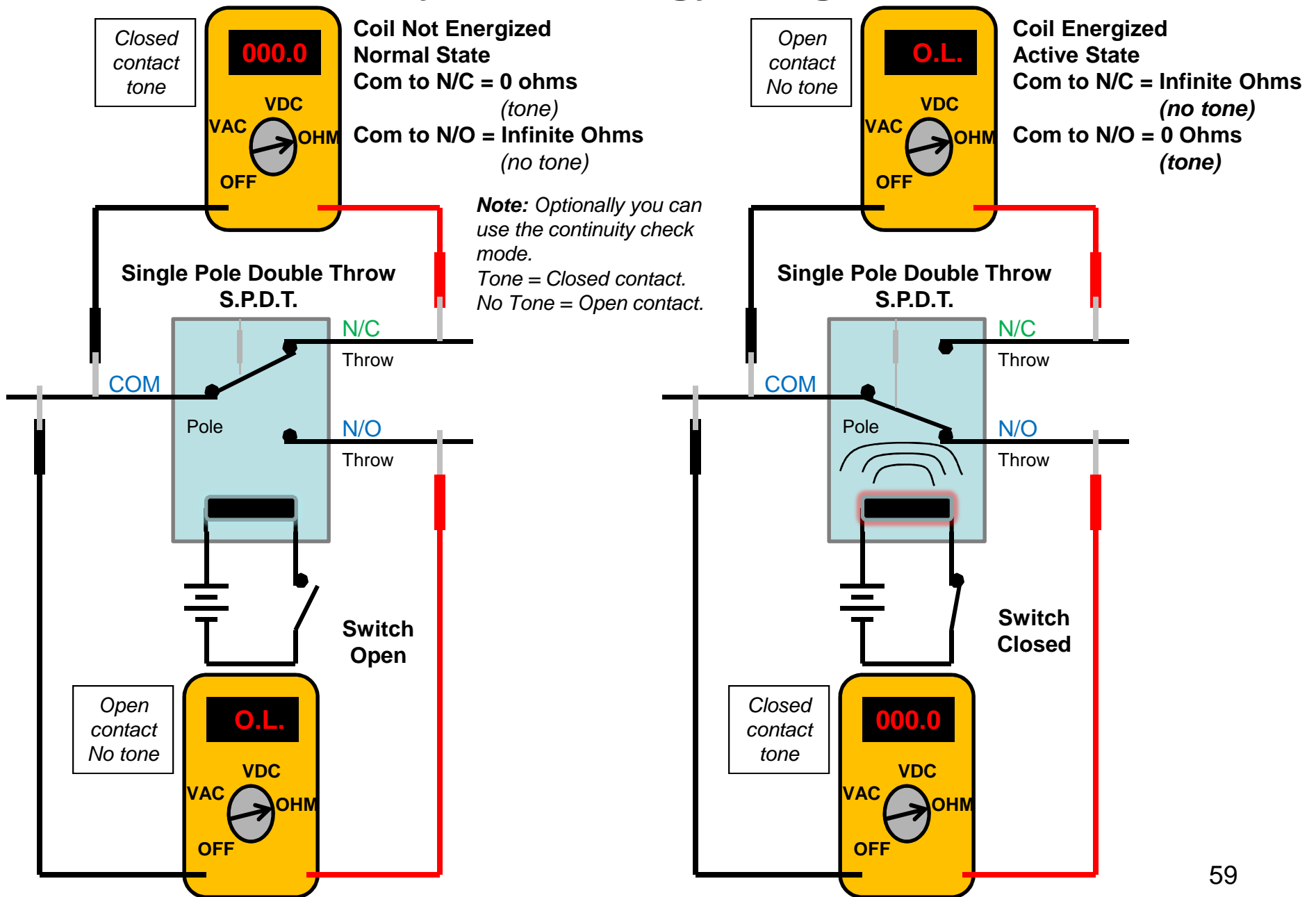
Single Pole Double Throw
S.P.D.T.



Single Pole Double Throw
S.P.D.T.

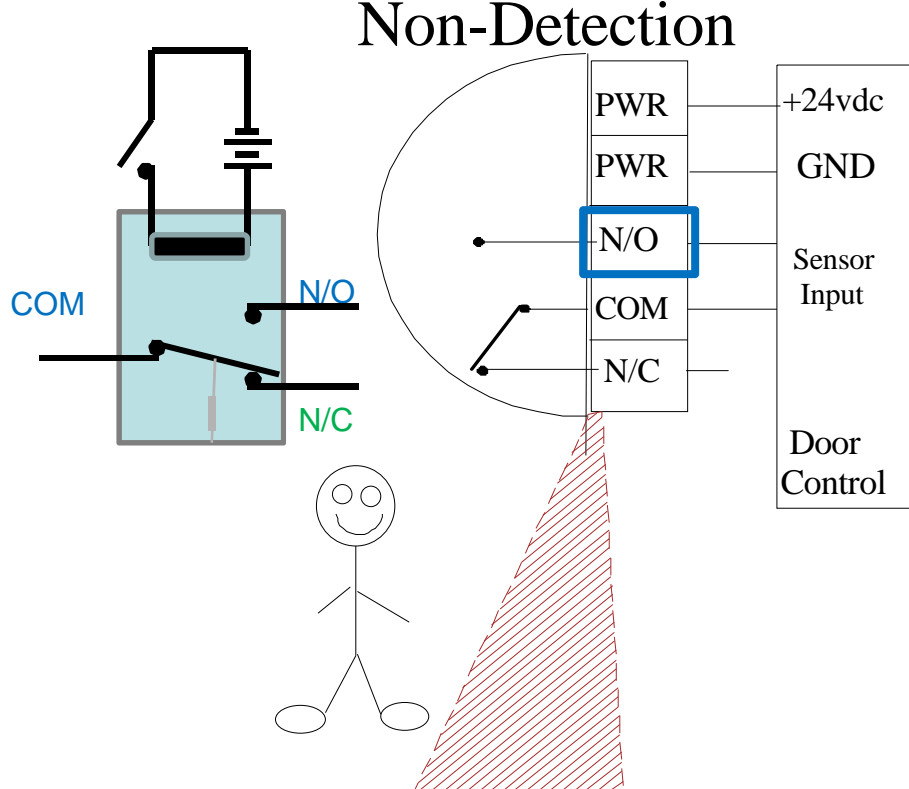


Relay Terminology / Logic

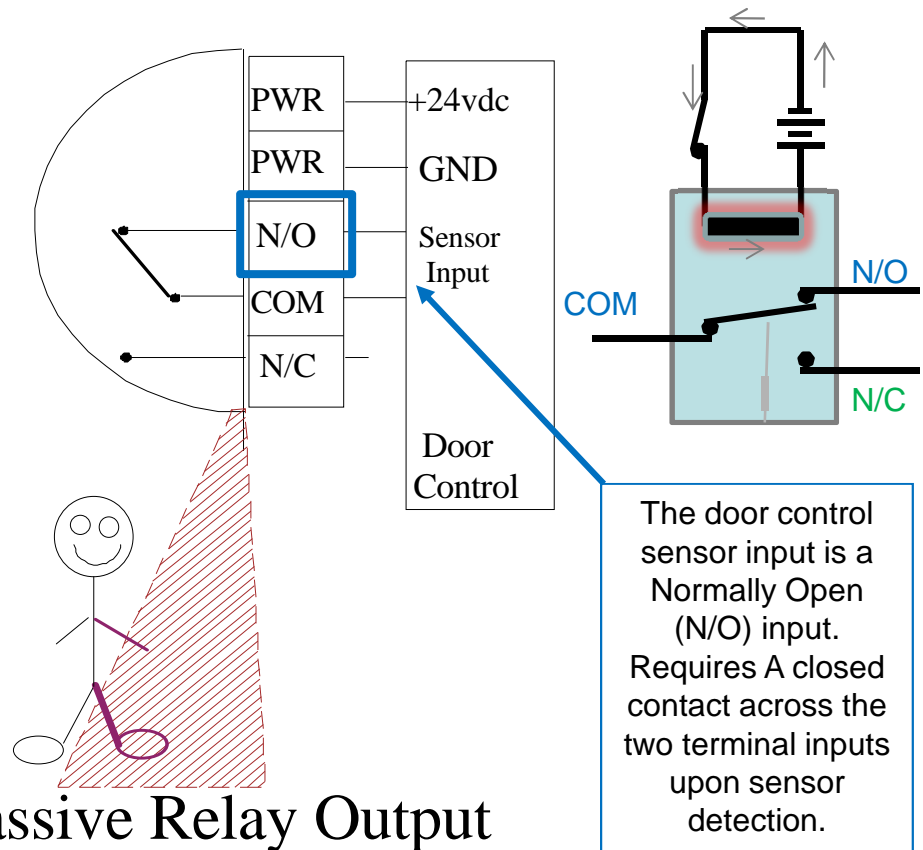


ACTIVE vs. PASSIVE Relays (Sensors)

Passive Relay Output Non-Detection

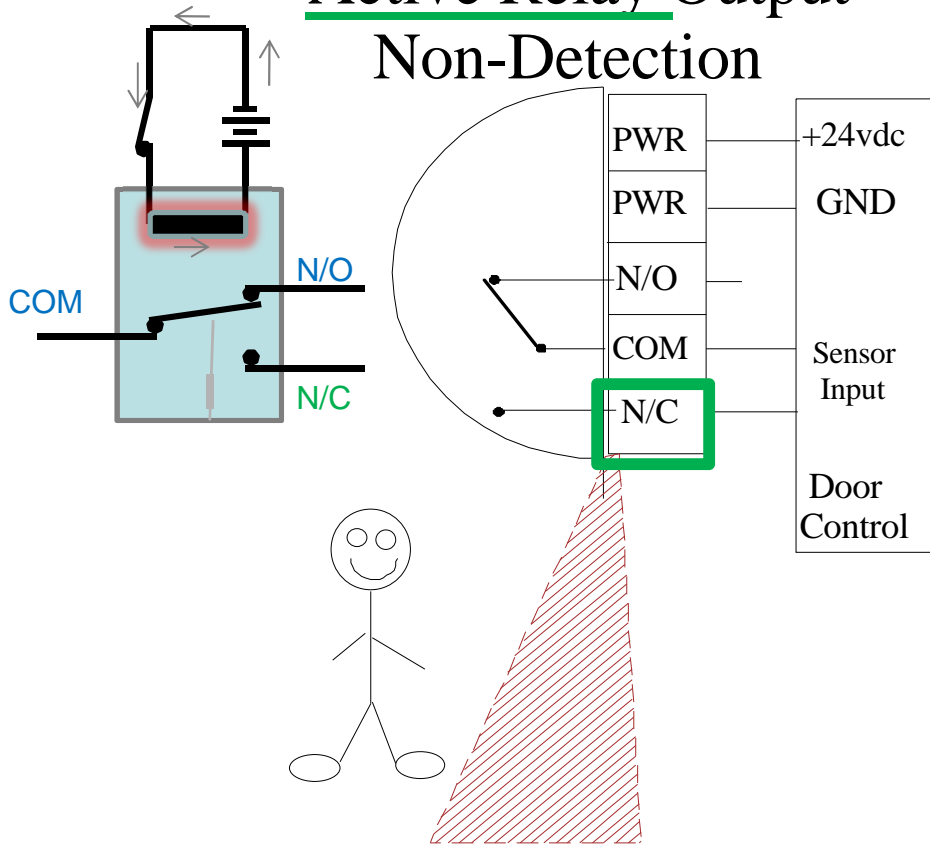


Passive Relay Output Detection

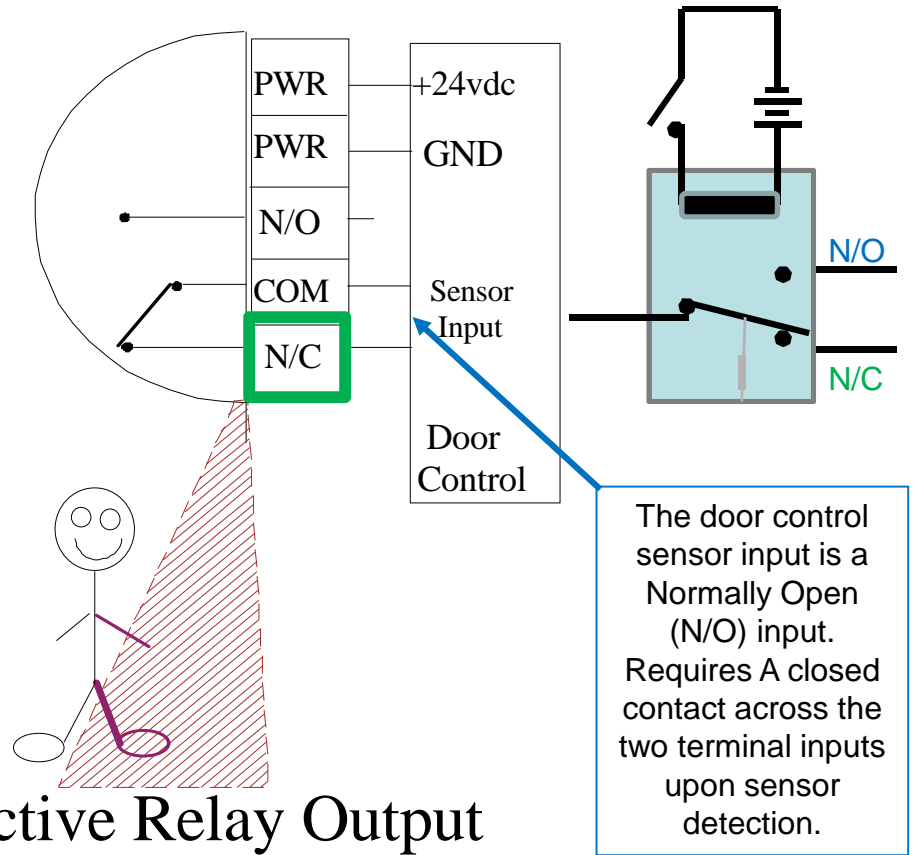


ACTIVE vs. PASSIVE Relays (Sensors)

Active Relay Output Non-Detection

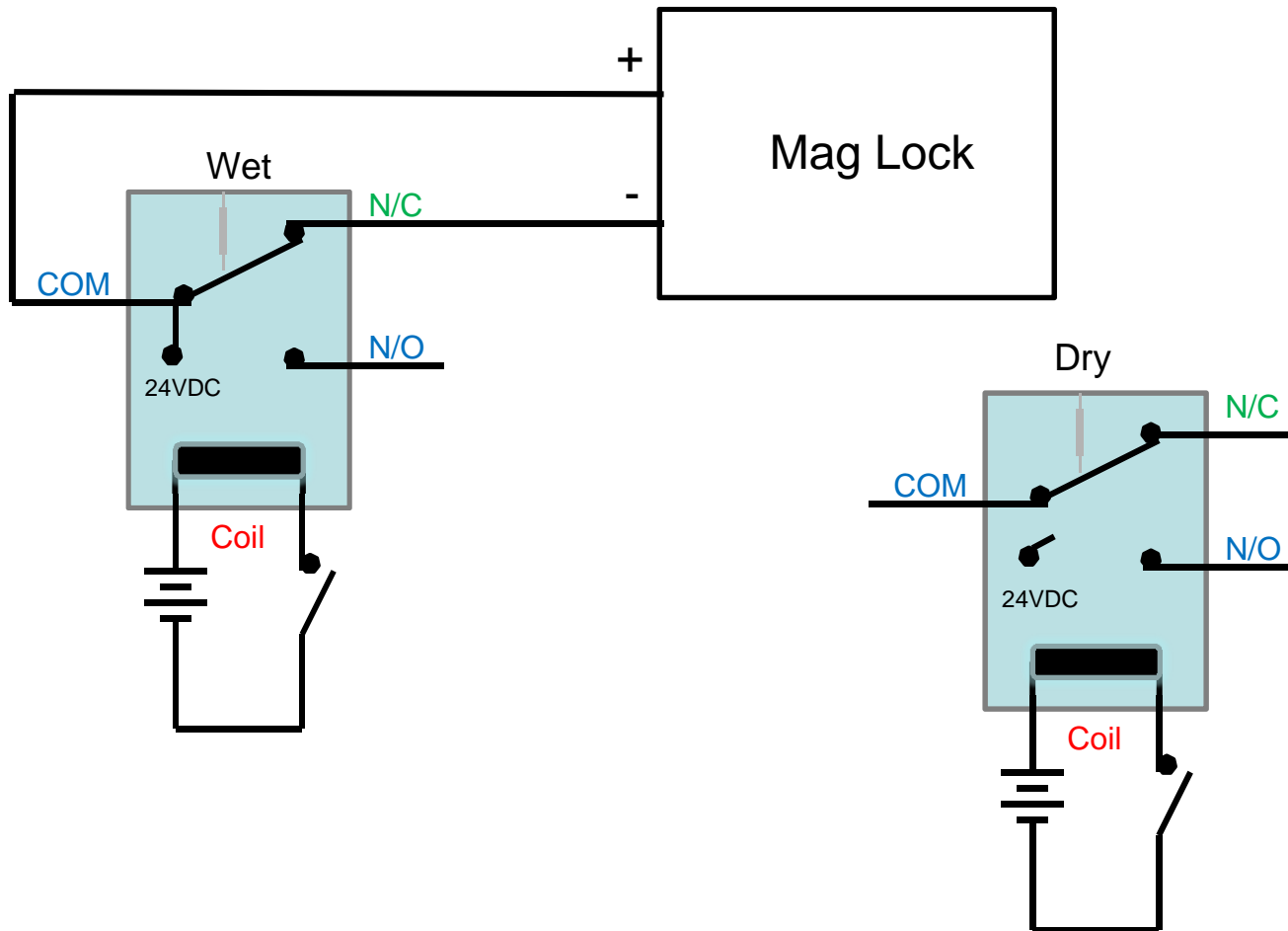


Active Relay Output Detection



WET vs. DRY Relay Output

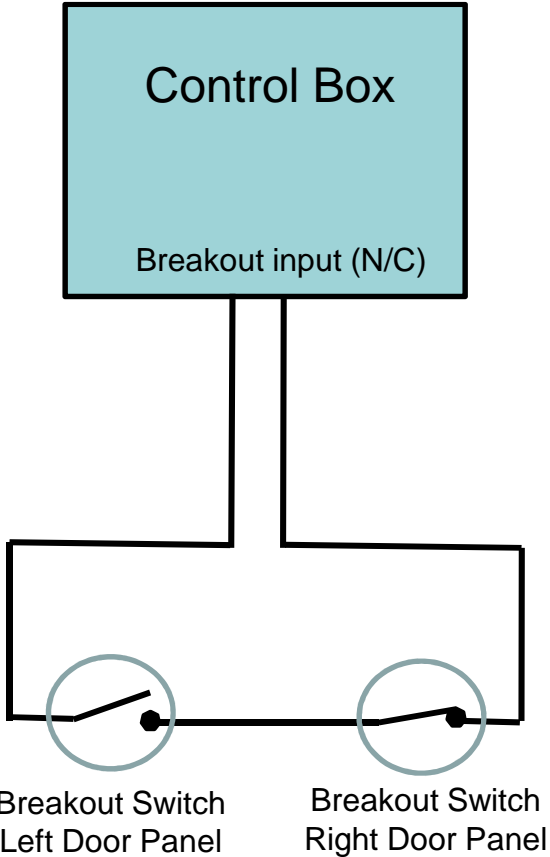
A **WET output relay** actually applies some sort of voltage to the connected equipment. Generally a voltage is applied to the COM and transferred to the N.O. or N.C. contact, which in turn is applied to the connected equipment. Wet output relays are generally used for applying voltage to a device such as a magnetic lock or an electric strike.



N/C inputs vs. N/O inputs

(Series) vs. (Parallel)

N/C sensor inputs with multiple sensors
Sensors must be connected in series
with the input



N/O sensor inputs with multiple sensors
Sensors must be connected in parallel
with the input

